Homework #9
Economics D11, Fall 2000.
Due Wednesday, December 4.

The purpose of this question is to give you a 'hands on' acquaintance with linearization as a strategy for solving a model. In addition, you will use this tool to shed light on one possible factor, lack of substitutability between capital and labor, that may help account for comovement of labor inputs over the business cycle.

Consider a model in which the preferences of the representative agent are given by:

$$E_0 \sum_{t=0}^{\infty} \beta^t u(c_t, n_t), \quad u(c, n) = \frac{c (1 - n)^\psi}{1 - \sigma}^{1-\sigma}, \quad 0 < \beta < 1,$$

where $\psi, \sigma > 0$, and satisfy the other restrictions needed for strict concavity (see the handout on bringing hours worked into the neoclassical growth model.) Suppose the resource constraint is given by

$$c_t + k_{t+1} - (1 - \delta)k_t \leq \left[ (\alpha k_t \delta + (1 - \alpha) n_t \nu) \right]^{\frac{\nu-1}{\nu}} \cdot \zeta_t^\nu \cdot \exp(z_t) \equiv f(k_t, n_t, z_t),$$

where $\delta, 1 - \delta, \nu > 0$ and $z_t$ has the following statistical representation:

$$z_t = \rho z_{t-1} + \varepsilon_t, \quad |\rho| < 1,$$

where $\varepsilon_t$ is a zero mean random variable that is independently distributed over time. Note that the mean of $z_t$ is zero. Here, $k_0 > 0$ is given and the restrictions are $n_0, k_{t+1}, 1-n_t, c_t \geq 0$, for $t = 0, 1, 2, \ldots$. We know that when $\nu = 1$, then the model is incapable of generating comovement in employment across the consumption and investment sectors. The purpose of this question is to explore the model's ability to account for comovement when $\nu \neq 1$.

1. The solution to the planning problem associated with the above model is a set of policy rules, $n = h(k, z)$, and $k' = g(k, z)$. Explain why these also characterize the aggregate employment and capital decisions in the underlying Arrow-Debreu or Sequence of Markets equilibrium.
2. We can interpret the above model as a ‘reduced form’ for a particular two sector model with the following specification of technology:

$$c_t \leq f(k_{ct}, n_{ct}, z_t), \quad i_t \leq f(k_{it}, n_{it}, z_t),$$

and the following additional restrictions:

$$n_{ct}, n_{ct}, k_{ct}, k_{it} \geq 0, \quad k_{ct} + k_{it} = k_t, \quad n_{ct} + n_{it} = n_t.$$ 

Show that the policy rule for $n_c$ is as follows:

$$n_c(k, z) = \left(1 - \frac{\alpha}{\varphi}\right)^{\nu} (1 - h(k, z))^{\nu} \left(\frac{c(k, z)}{\exp(z)}\right)^{1-\nu}, \quad (1)$$

where $c(k, z)$ is the policy rule for consumption:

$$c(k, z) = f(k, h(k, z), z) + (1 - \delta)k - g(k, z).$$

(Hint: think about the labor first order condition in the two-sector version of the economy.)

3. The share of income paid to labor, $s_t$, is defined as

$$s_t = \frac{W_t n_t}{y_t},$$

where $y_t = f(k_t, n_t, z_t)$ and $W_t$ is the wage rate in the underlying market economy. Show that, in nonstochastic steady state,

$$1 - s = \alpha^{\nu} \left[\frac{1}{\beta + \delta - 1}\right]^{1-\nu}.$$ 

From this relationship we see a potentially important difference between the $\nu = 1$ and the $\nu \neq 1$ cases. When $\nu = 1$, then $s = 1 - \alpha$. Both of these are independent of the time unit in the model. However, when $\nu \neq 1$, the formula involves a mixture of variables denominated in units of time ($\beta$ and $\delta$) and variables that do not have a time dimension ($s, \alpha, \nu$). For example, if in an annual model $\beta = 1/1.03$ makes sense, then $\beta = 1/1.03^{25}$ is the corresponding quarterly discount factor. If $\delta = .08$ makes sense at an annual frequency, then
\[ \delta = 1 - (1 - .08)^{25} \approx .08/4 \] is the corresponding quarterly rate. These observations have an important implication. To see this, rewrite the above expression:

\[
\alpha = \left\{ (1 - s) \left[ \frac{1}{\beta} + \delta - 1 \right]^{\nu - 1} \right\}^{1/\nu}.
\]

Suppose our strategy for estimating \( \alpha \) is to set it to the value that is compatible with the sample average of labor’s share, \( s \), the Department of Commerce’s estimate of \( \delta \) and values for \( \beta \) and \( \nu \) based on other information. If for some reason, say to get the right amount of comovement of labor across sectors, we wanted to make \( \nu \) small, but we didn’t want to violate the constraint, \( \alpha < 1 \), then we might prefer to go to an annual, rather than a quarterly specification for the model. This would make \( 1/\beta + \delta - 1 \) large and, hence, increase the likelihood that \( (1 - s)/[1/\beta + \delta - 1] < 1 \), so that \( \alpha \leq 1 \) as \( \nu \to 0 \). Thus, when we allow \( \nu \neq 1 \), the choice of time unit for the model can matter when trying to ‘fit’ various first moments of the data. For example, suppose \( s = 0.64, \delta = .10, \beta = 1/1.05 \). Then, \( \alpha = 0.7 \), after rounding. But, if we use the quarterly analogs of the parameters with a time dimension, so that \( \delta = .026 \) and \( \beta = 1/1.0123 \), then the above formula implies \( \alpha = 1.95 \), after rounding.

4. By inspecting (1) it is obvious that when \( \nu = 1 \), there cannot be comovement in labor inputs across sectors. This is a very big problem, since comovement is perhaps the most fundamental feature of business cycles. We shall investigate whether comovement is possible with \( \nu \neq 1 \). We want \( n_c \) and \( n_t \) to both go up in response to a positive shock to \( z \) which raises output. Give an intuitive explanation, using (1), why raising \( \nu \) might increase the likelihood of getting comovement.

5. The only way to find out if there is comovement, is to do some computations. We shall compute

\[
\frac{1}{n_c(k, z)} \frac{dn_c(k, z)}{dz}, \quad \frac{1}{n_t(k, z)} \frac{dn_t(k, z)}{dz},
\]

evaluating all variables in non-stochastic (replacing \( z \) by \( Ez = 0 \)) steady state. The objective is to get these to have the same sign and the
second to be about twice as large as the first. The computation will rely fundamentally on the linearization solution strategy we discussed in class. You should use the following parameter values: $\psi = 3$, $\sigma = 2$, $\rho = .9$, $\beta = 1/1.05$, $\delta = .10$, $\nu = 2.5$, $\alpha = .58$.

(a) Compute the steady state values of $n$, $c$, $y$, $n_c$, $n_i$, $k$, $s$, $k/y$.

(b) Compute $u_c$, $u_{cc}$, $u_{cn}$, $u_n$, $u_{nn}$, $F = y + (1 - \delta)k$, $F_k$, $F_{kk}$, $F_n$, $F_{nn}$, $F_z$, $F_{nz}$, $F_{bz}$. These are the derivatives of the various functions, evaluated in nonstochastic steady state. Here, $F$ is $f + (1 - \delta)k$, where $f$ is the function defined above. Also it is convenient to define the function $w(c, n) = -u_n(c, n)/u_c(c, n)$. Compute $w$, $w_c$, $w_n$. Again, these are evaluated in the nonstochastic steady state. All these numbers are things that go into constructing the linearized Euler equations. If it is convenient to compute these separately.

(c) Write the Euler equations as:

$$E \left[ R(k_t, k_{t+1}, k_{t+2}, n_t, n_{t+1}, \z_t, \z_{t+1}) | \z_t \right] = 0,$$

$$h(k_t, k_{t+1}, n_t, \z_t) = 0.$$

Obtain the coefficients in the first order Taylor series expansion of $R$ and $h$ about the non-stochastic, steady state values of the arguments. Use the linearized $h$ to solve for $n_t$ in terms of $k_t$, $k_{t+1}$, $\z_t$. Use this expression to substitute out for $n_t$, $n_{t+1}$ in the linearized version of $R$. The resulting expression can be written:

$$0 = E \left[ g_h(k_t - k) + g_{k}(k_{t+1} - k) + g_{k^2}(k_{t+2} - k) + g_{z} \z_t + g_{z'} \z_{t+1}| \z_t \right].$$

Report the values for $g_i$, $i = k, k', k''$, $z, z'$. Here, $k$ is the non-stochastic steady state value of the capital stock.

(d) Posit the following policy rule for capital:

$$k_{t+1} = k + \alpha_0 (k_t - k) + \alpha_1 \z_t.$$ 

Find the values of $|\alpha_0| < 1$ and $\alpha_1$ which solve the linearized Euler equation. Using the expression for $n_t$ in terms of $k_t$, $k_{t+1}$, $\z_t$ and the policy rule for capital to find $\beta_0$, $\beta_1$ in:

$$n_t = n + \beta_0 (k_t - k) + \beta_1 \z_t.$$
(e) Compute the derivatives discussed above by linearizing the mapping to the employment decision and the investment decision, and making use of the values you obtained for $\alpha_1$ and $\beta_1$.

(f) So, do you get comovement?

(g) Suppose $\varepsilon_1 = 1$, and $\varepsilon_t = 0$ for $t \neq 1$. Set $s_0 = 1$ and compute $s_1$, $s_2$, $s_3$, $s_4$. Set $k_1$ and $z_0$ equal to their steady state values. Compute $c_t$, $n_t$, $I_t$, for $t = 1, 2, 3, 4$, and calculate the percent difference between these and their steady state values (i.e., what they would have been if $\varepsilon_t$ had been held constant at zero.) Note how much stronger the percentage response of investment is, compared with the response in consumption.