

...

Discussion of:
Chari-Kehoe-McGrattan:
**Are Structural VARs Useful Guides for Developing
Business Cycle Theories?**
by Larry Christiano

...

Chari-Kehoe-McGrattan:
**Are Structural VARs Useful Guides for Developing
Business Cycle Theories?**

- Jordi Gali Estimated the Dynamic Effects of Technology Shocks By Exploiting Three (Identification) Assumptions:
 - a. Tech Shocks Are a Linear Combination of a Finite Number of Lags of Past Data.
 - b. Tech Shocks Are Orthogonal to Other Structural Shocks.
 - c. Tech Shocks are the **Only** Shocks that Have Long Run Effects on Labor Productivity.

...

Chari-Kehoe-McGrattan:
**Are Structural VARs Useful Guides for Developing
Business Cycle Theories?**

- Jordi Gali Estimated the Dynamic Effects of Technology Shocks By Exploiting Three (Identification) Assumptions:
 - a. Tech Shocks Are a Linear Combination of a Finite Number of Lags of Past Data.
 - b. Tech Shocks Are Orthogonal to Other Structural Shocks.
 - c. Tech Shocks are the **Only** Shocks that Have Long Run Effects on Labor Productivity.
- Technically, CKM's Paper is a Critique of Jordi Gali's Paper:
 - Argue that Gali's Methods Produce Severely Distorted Estimates of Impulse Response Functions.

...

Chari-Kehoe-McGrattan:
**Are Structural VARs Useful Guides for Developing
Business Cycle Theories?**

- Jordi Gali Estimated the Dynamic Effects of Technology Shocks By Exploiting Three (Identification) Assumptions:
 - a. Tech Shocks Are a Linear Combination of a Finite Number of Lags of Past Data.
 - b. Tech Shocks Are Orthogonal to Other Structural Shocks.
 - c. Tech Shocks are the **Only** Shocks that Have Long Run Effects on Labor Productivity.
- Technically, CKM's Paper is a Critique of Jordi Gali's Paper:
 - Argue that Gali's Methods Produce Severely Distorted Estimates of Impulse Response Functions.
- CKM Do Not Think of This as a Narrow Comment on Gali Alone.
 - They Conjecture that their Critique Applies to VAR Methods More Generally.

...

Chari-Kehoe-McGrattan:
**Are Structural VARs Useful Guides for Developing
Business Cycle Theories?**

- Jordi Gali Estimated the Dynamic Effects of Technology Shocks By Exploiting Three (Identification) Assumptions:
 - a. Tech Shocks Are a Linear Combination of a Finite Number of Lags of Past Data.
 - b. Tech Shocks Are Orthogonal to Other Structural Shocks.
 - c. Tech Shocks are the **Only** Shocks that Have Long Run Effects on Labor Productivity.
- Technically, CKM's Paper is a Critique of Jordi Gali's Paper:
 - Argue that Gali's Methods Produce Severely Distorted Estimates of Impulse Response Functions.
- CKM Do Not Think of This as a Narrow Comment on Gali Alone.
 - They Conjecture that their Critique Applies to VAR Methods More Generally.
- So, the Answer to the Question in the title of the Paper is **NO!**

...

- CKM Conclusion: Identified VARs Are of No Use As A Guide for Developing Business Cycle Theories.
 - Based On Three Numerical Examples.

...

- CKM Conclusion: Identified VARs Are of No Use As A Guide for Developing Business Cycle Theories.
 - Based On Three Numerical Examples,
- The Examples Fail to Establish CKM's Case.

...

- CKM Conclusion: Identified VARs Are of No Use As A Guide for Developing Business Cycle Theories.
 - Based On Three Numerical Examples,
- The Examples Fail to Establish CKM's Case.
- In Two Examples: Distortions Occur Because Gali's Identification Assumptions Do Not Hold.
 - They Illustrate the Principle:

| |
|---|
| If You Make the Wrong Identification Assumption |
| Then You Get the Wrong Answer |

...

- CKM Conclusion: Identified VARs Are of No Use As A Guide for Developing Business Cycle Theories.
 - Based On Three Numerical Examples,
- The Examples Fail to Establish CKM's Case.
- In Two Examples: Distortions Occur Because Gali's Identification Assumptions Do Not Hold.
 - They Illustrate the Principle:

| |
|---|
| If You Make the Wrong Identification Assumption |
| Then You Get the Wrong Answer |
 - Problem: Simply Pointing Out this Principle Does Not Establish That Gali Actually Did Make the Wrong Assumption, or that He Got the Wrong Answer.
 - The Examples are Not New or Surprising.

...

- CKM Conclusion: Identified VARs Are of No Use As A Guide for Developing Business Cycle Theories.
 - Based On Three Numerical Examples,
- The Examples Fail to Establish CKM's Case.
- In Two Examples: Distortions Occur Because Gali's Identification Assumptions Do Not Hold.
 - They Illustrate the Principle:

| |
|---|
| If You Make the Wrong Identification Assumption |
| Then You Get the Wrong Answer |
 - Problem: Simply Pointing Out this Principle Does Not Establish That Gali Actually Did Make the Wrong Assumption, or that He Got the Wrong Answer.
 - The Examples are Not New or Surprising.
- A Third Example:
 - Numerical Example In Which Gali's Assumptions Are True, and Estimation Is Nevertheless Distorted.
 - This Example Potentially Interesting, Is it a Problem in Practice?
 - Distortions Not Present in a Recent VAR Analysis.

...

Outline

- Overview (done!)
- Long Run Identification
- Equilibrium Model Used in Examples.
- The Three Examples
- Conclusion

...

Long-Run Identification

- Data:

$$\text{DSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}, \quad \text{LSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ l_t \end{bmatrix}$$

...

Long-Run Identification

- Data:

$$\text{DSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}, \quad \text{LSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ l_t \end{bmatrix}$$

- Vector Autoregression:

$$Y_t = B(L)Y_{t-1} + u_t, \quad Eu_t u_t' = V.$$

...

Long-Run Identification

- Data:

$$\text{DSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}, \quad \text{LSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ l_t \end{bmatrix}$$

- Vector Autoregression:

$$Y_t = B(L)Y_{t-1} + u_t, \quad E u_t u_t' = V.$$

- Assumption about Fundamental Economic Shocks, ε_t :

$$u_t = C \varepsilon_t, \quad C C' = V,$$
$$\varepsilon_t = \begin{pmatrix} \varepsilon_{\text{technology},t} \\ \varepsilon_{\text{other},t} \end{pmatrix}$$

- In General:

$$\lim_{j \rightarrow \infty} E_t \log \left(\frac{y_{t+j}}{l_{t+j}} \right) = a \times \varepsilon_{\text{technology},t} + b \times \varepsilon_{\text{other},t}.$$

...

Long-Run Identification

- Data:

$$\text{DSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}, \quad \text{LSVAR: } Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ l_t \end{bmatrix}$$

- Vector Autoregression:

$$Y_t = B(L)Y_{t-1} + u_t, \quad E u_t u_t' = V.$$

- Assumption about Fundamental Economic Shocks, ε_t :

$$u_t = C \varepsilon_t, \quad C C' = V,$$
$$\varepsilon_t = \begin{pmatrix} \varepsilon_{\text{technology},t} \\ \varepsilon_{\text{other},t} \end{pmatrix}$$

- In General:

$$\lim_{j \rightarrow \infty} E_t \log \left(\frac{y_{t+j}}{l_{t+j}} \right) = a \times \varepsilon_{\text{technology},t} + b \times \varepsilon_{\text{other},t}.$$

- Long Run Identification Assumption:

$$b = 0.$$

...

Examples Constructed Using Variants of Following Model

- Resource Constraint:

$$c_t + G_t + k_{t+1} = k_t^\alpha (Z_t l_t)^{1-\alpha} + (1 - \delta)k_t$$

- Intratemporal Euler equation:

$$\frac{U_{leisure,t}}{U_{c,t}} = (1 - \tau_{lt})F_{l,t}$$

- Intertemporal Euler equation:

$$U_{c,t}(1 + \tau_{xt}) = \beta E_t U_{c,t+1} [F_{k,t+1} + (1 - \delta)(1 + \tau_{x,t+1})]$$

- Exogenous Processes:

$$Z_t, \tau_{lt}, \tau_{xt}, G_t$$

- Three Examples: Alternative Specifications of Exogenous Processes.

...

Examples

- Example #1: DSVAR Analysis Distorted by ‘Invertibility Problems’
- Example #2: An RBC Model Fit by Maximum Likelihood Methods to US Data Implies Identification Based on Long-Run Restrictions Severely Distorted.
- Example #3: Even when Identifying Restrictions Correct, Estimates of Impulse Response Functions Hopelessly Imprecise.

...

Example #1 Invertibility

- Exogenous Shocks:

$$\begin{pmatrix} \Delta \log Z_t \\ \tau_{lt} \end{pmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0.938 \end{bmatrix} \begin{pmatrix} \Delta \log Z_{t-1} \\ \tau_{lt-1} \end{pmatrix} + \begin{pmatrix} \varepsilon_{\text{technology},t} \\ \varepsilon_{\text{other},t} \end{pmatrix}$$

- Model Prediction: DSVAR Analysis Finds Hours Fall After Positive Shock To Technology, Even Though In Data Generating Mechanism Hours Rises.

...

- (Partial) Explanation:

- RBC Model Implies l_t Stationary. So, there is **NO VAR** representation for

$$Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}.$$

...

- (Partial) Explanation:

- RBC Model Implies l_t Stationary. So, there is **NO VAR** representation for

$$Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}.$$

- Example: Suppose hours stationary in levels -

$$l_t = \rho l_{t-1} + \varepsilon_t, \quad -1 < \rho < 1$$

so,

$$\Delta l_t = \rho \Delta l_{t-1} + \varepsilon_t - \varepsilon_{t-1}.$$

...

- (Partial) Explanation:

- RBC Model Implies l_t Stationary. So, there is **NO VAR** representation for

$$Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}.$$

- Example: Suppose hours stationary in levels -

$$l_t = \rho l_{t-1} + \varepsilon_t, \quad -1 < \rho < 1$$

so,

$$\Delta l_t = \rho \Delta l_{t-1} + \varepsilon_t - \varepsilon_{t-1}.$$

Try and ‘invert’ this, i.e., express ε_t as function of current and past Δl_t ’s:

$$\Delta l_t = (\rho - 1) [\Delta l_{t-1} + \Delta l_{t-2} + \Delta l_{t-3} + \dots] + \varepsilon_t$$

Can’t do it...Not Invertible.

...

- (Partial) Explanation:

- RBC Model Implies l_t Stationary. So, there is **NO VAR** representation for

$$Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}.$$

- Example: Suppose hours stationary in levels -

$$l_t = \rho l_{t-1} + \varepsilon_t, \quad -1 < \rho < 1$$

so,

$$\Delta l_t = \rho \Delta l_{t-1} + \varepsilon_t - \varepsilon_{t-1}.$$

Try and ‘invert’ this, i.e., express ε_t as function of current and past Δl_t ’s:

$$\Delta l_t = (\rho - 1) [\Delta l_{t-1} + \Delta l_{t-2} + \Delta l_{t-3} + \dots] + \varepsilon_t$$

Can’t do it...Not Invertible.

- VAR For Y_t Is Misspecified, Regardless of Lag Length.

...

- (Partial) Explanation:

- RBC Model Implies l_t Stationary. So, there is **NO VAR** representation for

$$Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}.$$

- Example: Suppose hours stationary in levels -

$$l_t = \rho l_{t-1} + \varepsilon_t, \quad -1 < \rho < 1$$

so,

$$\Delta l_t = \rho \Delta l_{t-1} + \varepsilon_t - \varepsilon_{t-1}.$$

Try and ‘invert’ this, i.e., express ε_t as function of current and past Δl_t ’s:

$$\Delta l_t = (\rho - 1) [\Delta l_{t-1} + \Delta l_{t-2} + \Delta l_{t-3} + \dots] + \varepsilon_t$$

Can’t do it...Not Invertible.

- VAR For Y_t Is Misspecified, Regardless of Lag Length.
- In Practice, This Problem Need not be Fatal. There Exist Methods That Can be Used to Assess Whether Hours Worked Should Be Differenced, Or Not (see recent literature).

...

- (Partial) Explanation:

- RBC Model Implies l_t Stationary. So, there is **NO VAR** representation for

$$Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ \Delta l_t \end{bmatrix}.$$

- Example: Suppose hours stationary in levels -

$$l_t = \rho l_{t-1} + \varepsilon_t, \quad -1 < \rho < 1$$

so,

$$\Delta l_t = \rho \Delta l_{t-1} + \varepsilon_t - \varepsilon_{t-1}.$$

Try and ‘invert’ this, i.e., express ε_t as function of current and past Δl_t ’s:

$$\Delta l_t = (\rho - 1) [\Delta l_{t-1} + \Delta l_{t-2} + \Delta l_{t-3} + \dots] + \varepsilon_t$$

Can’t do it...Not Invertible.

- VAR For Y_t Is Misspecified, Regardless of Lag Length.
- In Practice, This Problem Need not be Fatal. There Exist Methods That Can be Used to Assess Whether Hours Worked Should Be Differenced, Or Not (see recent literature).
- Findings of Example #1 Closely Related to Similar Findings in Altig, Christiano, Eichenbaum and Linde (2002), Christiano, Eichenbaum and Vigfusson (2004a,2004b).

...

Example #1 Invertibility, cont'd

- Source of Non-Invertibility Explored Here: Data Overdifferencing

...

Example #1 Invertibility, cont'd

- Source of Non-Invertibility Explored Here: Data Overdifferencing
- Other Sources of Non-Invertibility
 - Lippi-Reichlin: Technology Growth Follows Diffusion Process:

$$\Delta \log (Z_t) = \varepsilon_{\text{technology},t} + 2 \times \varepsilon_{\text{technology},t-1}.$$

May Not Be Able to Recover $\varepsilon_{\text{technology},t}$ From Past Data.

...

Example #1 Invertibility, cont'd

- Source of Non-Invertibility Explored Here: Data Overdifferencing
- Other Sources of Non-Invertibility
 - Lippi-Reichlin: Technology Growth Follows Diffusion Process:

$$\Delta \log(Z_t) = \varepsilon_{\text{technology},t} + 2 \times \varepsilon_{\text{technology},t-1}.$$

May Not Be Able to Recover $\varepsilon_{\text{technology},t}$ From Past Data.

- Can Generate Other Examples (Hansen and Sargent).

...

Example #1 Invertibility, cont'd

- Source of Non-Invertibility Explored Here: Data Overdifferencing
- Other Sources of Non-Invertibility

- Lippi-Reichlin: Technology Growth Follows Diffusion Process:

$$\Delta \log(Z_t) = \varepsilon_{\text{technology},t} + 2 \times \varepsilon_{\text{technology},t-1}.$$

- May Not Be Able to Recover $\varepsilon_{\text{technology},t}$ From Past Data.

- Can Generate Other Examples (Hansen and Sargent).

- Often: More Data in VAR Solves the Problem (Hansen-Sargent, Reichlin).

...

Example #1 Invertibility, cont'd

- Source of Non-Invertibility Explored Here: Data Overdifferencing
- Other Sources of Non-Invertibility
 - Lippi-Reichlin: Technology Growth Follows Diffusion Process:
$$\Delta \log (Z_t) = \varepsilon_{\text{technology},t} + 2 \times \varepsilon_{\text{technology},t-1}.$$
May Not Be Able to Recover $\varepsilon_{\text{technology},t}$ From Past Data.
 - Can Generate Other Examples (Hansen and Sargent).
 - Often: More Data in VAR Solves the Problem (Hansen-Sargent, Reichlin).
- These Sources of Non-Invertibility Deserve More Attention, But CKM are Silent About Them.

...

Example #2: A Model Estimated By Maximum Likelihood Implies Gali-Style VAR Identification Misleading

- Exogenous Shocks:

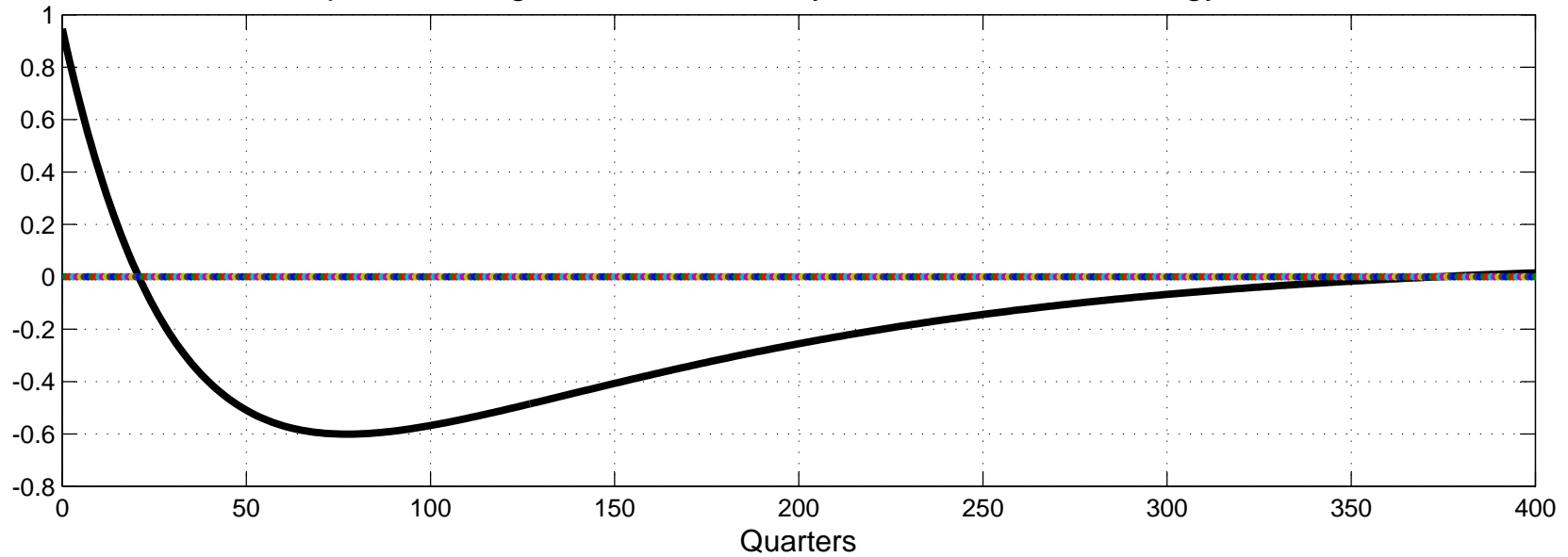
$$\begin{aligned} \log Z_t &= \alpha t + \log z_t, \\ \log G_t &= \beta t + \log g_t \end{aligned}$$
$$\begin{pmatrix} \log z_t \\ \tau_{lt} \\ \tau_{xt} \\ \log g_t \end{pmatrix} = P \begin{pmatrix} \log z_{t-1} \\ \tau_{lt-1} \\ \tau_{xt-1} \\ \log g_{t-1} \end{pmatrix} + Q \begin{pmatrix} \eta_{z,t} \\ \eta_{\tau_l,t} \\ \eta_{x,t} \\ \eta_{g,t} \end{pmatrix}.$$

- The matrix, Q Lower Triangular, $QQ' = V$.
- Enormous Persistence. Eigenvalues of P :

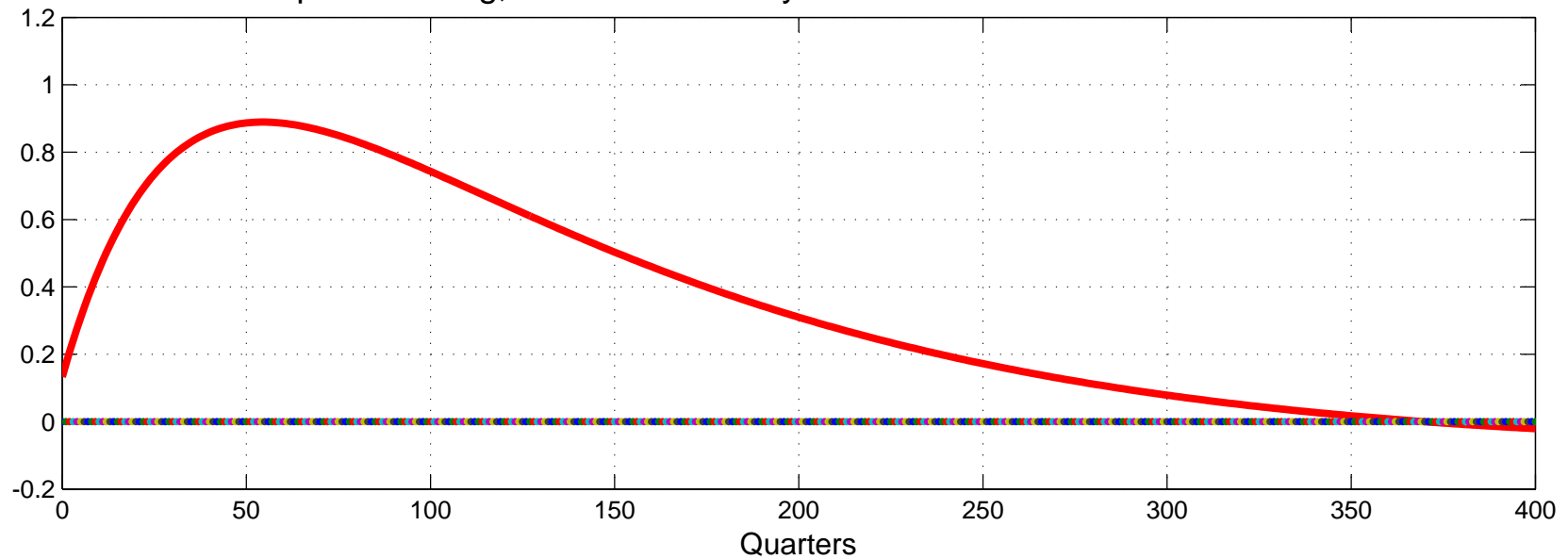
$$0.9952 \pm 0.0019i, 0.9927, 0.9598$$

Response to Shocks in CKM's Preferred Model

Response in Log, Labor Productivity to 1 std dev. Technology Shock



Response in Log, Labor Productivity to 1 std dev. Labor Tax Rate Shock



...

- Gali's Long Run Identification Assumptions Wrong in This Example
 - No Shock Has A Truly Permanent Effect
 - Two Shocks Do Have Highly Persistent Effects On Labor Productivity
 - No Surprise that Gali's Identification Assumptions Could Produce Highly Distorted Results In this Case.

...

- Gali's Long Run Identification Assumptions Wrong in This Example
 - No Shock Has A Truly Permanent Effect
 - Two Shocks Do Have Highly Persistent Effects On Labor Productivity
 - No Surprise that Gali's Identification Assumptions Could Produce Highly Distorted Results In this Case.
- Reader is Asked to take the Model Seriously Because it is Estimated Using Maximum Likelihood Methods.

...

- Gali's Long Run Identification Assumptions Wrong in This Example
 - No Shock Has A Truly Permanent Effect
 - Two Shocks Do Have Highly Persistent Effects On Labor Productivity
 - No Surprise that Gali's Identification Assumptions Could Produce Highly Distorted Results In this Case.
- Reader is Asked to take the Model Seriously Because it is Estimated Using Maximum Likelihood Methods.
 - A Literal Interpretation of the Model is Hard to Take Seriously
 - * Positive Innovation to Labor Tax \Rightarrow Labor Productivity Up Persistently.
 - * Positive Innovation to Technology \Rightarrow Labor Productivity Down.

...

- Gali's Long Run Identification Assumptions Wrong in This Example
 - No Shock Has A Truly Permanent Effect
 - Two Shocks Do Have Highly Persistent Effects On Labor Productivity
 - No Surprise that Gali's Identification Assumptions Could Produce Highly Distorted Results In this Case.
- Reader is Asked to take the Model Seriously Because it is Estimated Using Maximum Likelihood Methods.
 - A Literal Interpretation of the Model is Hard to Take Seriously
 - * Positive Innovation to Labor Tax \Rightarrow Labor Productivity Up Persistently.
 - * Positive Innovation to Technology \Rightarrow Labor Productivity Down.
 - Could Interpret CKM Model As Reduced Form of Another Model

...

- Gali's Long Run Identification Assumptions Wrong in This Example
 - No Shock Has A Truly Permanent Effect
 - Two Shocks Do Have Highly Persistent Effects On Labor Productivity
 - No Surprise that Gali's Identification Assumptions Could Produce Highly Distorted Results In this Case.
- Reader is Asked to take the Model Seriously Because it is Estimated Using Maximum Likelihood Methods.
 - A Literal Interpretation of the Model is Hard to Take Seriously
 - * Positive Innovation to Labor Tax \Rightarrow Labor Productivity Up Persistently.
 - * Positive Innovation to Technology \Rightarrow Labor Productivity Down.
 - Could Interpret CKM Model As Reduced Form of Another Model
 - * In That Deeper Structural Model, Gali's Assumption May Well Be Valid.

...

- Gali's Long Run Identification Assumptions Wrong in This Example
 - No Shock Has A Truly Permanent Effect
 - Two Shocks Do Have Highly Persistent Effects On Labor Productivity
 - No Surprise that Gali's Identification Assumptions Could Produce Highly Distorted Results In this Case.
- Reader is Asked to take the Model Seriously Because it is Estimated Using Maximum Likelihood Methods.
 - A Literal Interpretation of the Model is Hard to Take Seriously
 - * Positive Innovation to Labor Tax \Rightarrow Labor Productivity Up Persistently.
 - * Positive Innovation to Technology \Rightarrow Labor Productivity Down.
 - Could Interpret CKM Model As Reduced Form of Another Model
 - * In That Deeper Structural Model, Gali's Assumption May Well Be Valid.
 - * Possibility: There Could Be Just One Shock That Has A Permanent (or, Highly Persistent) Effect on Labor Productivity, Which Drives Both $\log Z$ and τ_{lt} .

...

- Gali's Long Run Identification Assumptions Wrong in This Example
 - No Shock Has A Truly Permanent Effect
 - Two Shocks Do Have Highly Persistent Effects On Labor Productivity
 - No Surprise that Gali's Identification Assumptions Could Produce Highly Distorted Results In this Case.
- Reader is Asked to take the Model Seriously Because it is Estimated Using Maximum Likelihood Methods.
 - A Literal Interpretation of the Model is Hard to Take Seriously
 - * Positive Innovation to Labor Tax \Rightarrow Labor Productivity Up Persistently.
 - * Positive Innovation to Technology \Rightarrow Labor Productivity Down.
 - Could Interpret CKM Model As Reduced Form of Another Model
 - * In That Deeper Structural Model, Gali's Assumption May Well Be Valid.
 - * Possibility: There Could Be Just One Shock That Has A Permanent (or, Highly Persistent) Effect on Labor Productivity, Which Drives Both $\log Z$ and τ_{lt} .
- Without Further Analysis, Not Clear What this Example Implies For Gali, or VAR Methods Generally.

...

Example #3: Impulse Response Functions Hard To Pin Down Even If Identification Assumptions Are Correct

- Exogenous Shocks:

$$\begin{pmatrix} \Delta \log Z_t \\ \tau_{lt} \end{pmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0.938 \end{bmatrix} \begin{pmatrix} \Delta \log Z_{t-1} \\ \tau_{lt-1} \end{pmatrix} + \begin{pmatrix} \varepsilon_{\text{technology},t} \\ \varepsilon_{\text{other},t} \end{pmatrix}$$

- Do LSVAR Analysis, with

$$Y_t = \begin{bmatrix} \Delta \log \left(\frac{y_t}{l_t} \right) \\ l_t \end{bmatrix}.$$

- No Over Differencing!
- Seems As Though There Should Be No Problem.

...

- Findings:
 - a. In Small Samples, Estimated Impulse Responses Have Very Large Sampling Variance
 - Analysis in Erceg, Guerrieri and Gust (2004) Suggests this May Be Because of High Persistence of τ_{lt}
 - b. Bias in Large Samples. Goes Away With Longer Lags in VAR.
- Would the Analyst Using Standard Diagnostic Tests for Lag Lengths Discover that Lag Lengths Need to Be Very Long?
 - If ‘Yes’ then the Example is Perhaps Less Worrisome.
- Do the Problems Go Away With More Data? Here is an Example Which Suggests that Maybe The Answer is ‘yes’.

...

Example #3, Cont'd

- Model Laboratory: Altig-Christiano-Eichenbaum-Linde Model, to be Presented and Defended Tomorrow by Marty.
- Model Parts:
 - Consumption, Investment, Employment, Transactions Motive for Holding Money Balances.
 - Investment Adjustment Costs, Wage Setting Frictions, Variable Capital Utilization.
 - Monetary Policy Shock, Neutral Shock to Technology (i.e., Z_t), Investment Specific Shock to Technology.

...

- Basic Business Cycle Properties of the Model:

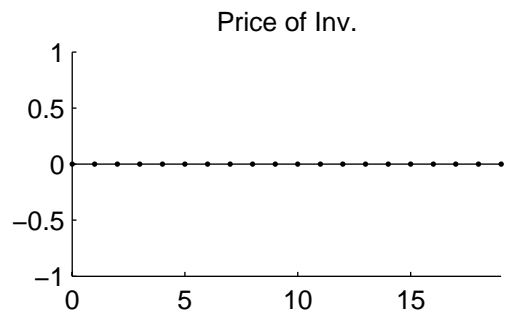
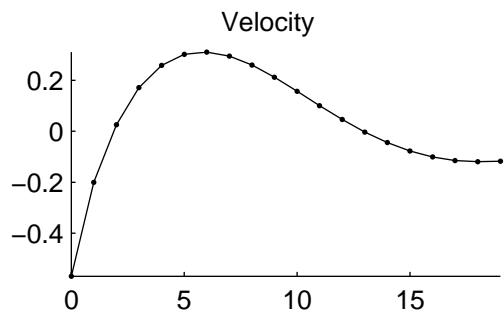
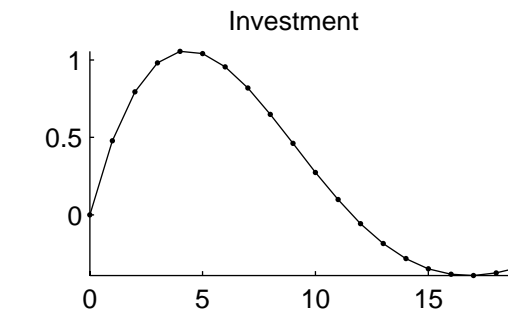
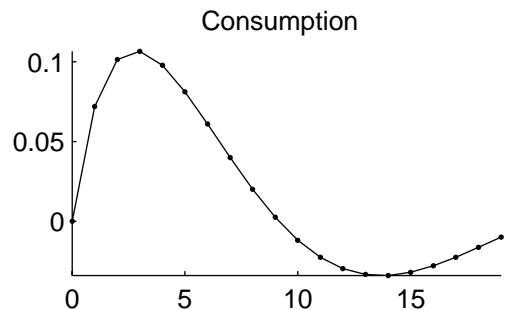
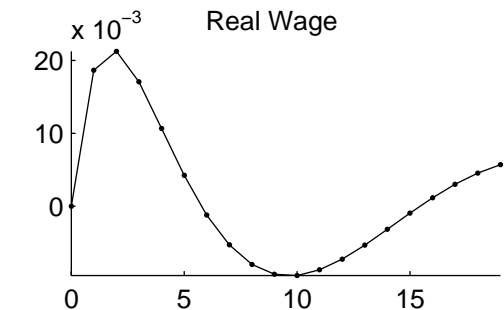
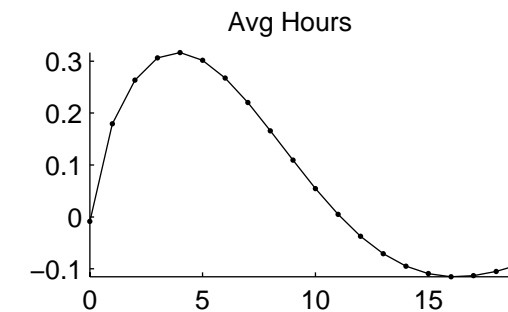
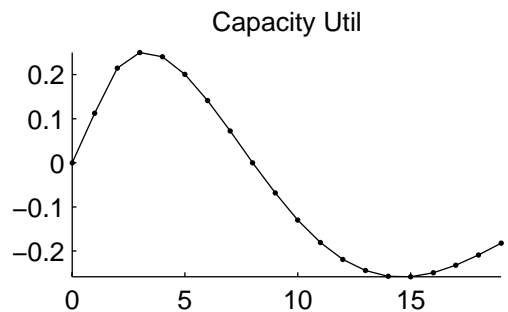
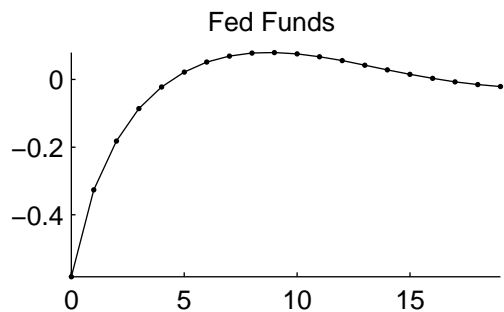
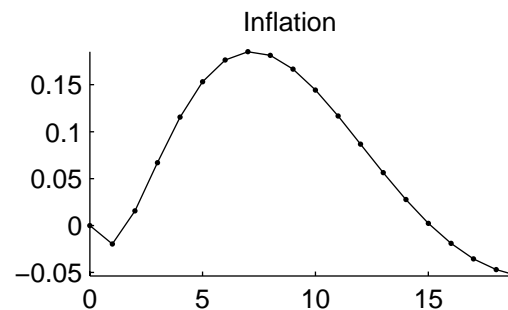
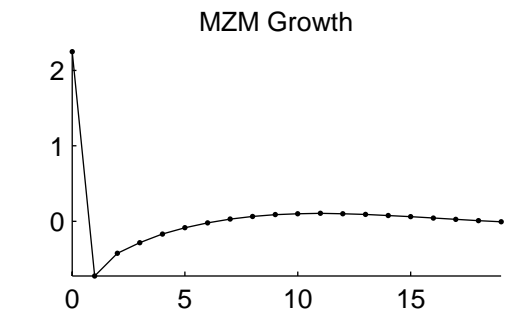
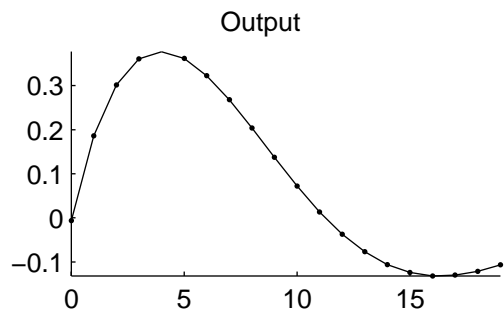
| Comparison of Model and Data: Kydland-Prescott Statistics | | | | |
|---|------------------|---------|-----------|---------|
| | (Rel.) Std. Dev. | | Corr. w/Y | |
| Variable | Model | US Data | Model | US Data |
| Output | 1.3 | 1.6 | 1 | 1 |
| Hours | 0.8 | 1.1 | 1.0 | 0.9 |
| Productivity | 0.3 | 0.5 | 0.8 | 0.07 |
| Wage | 0.2 | 0.5 | 0.4 | 0.1 |
| Consumption | 0.5 | 0.5 | 0.8 | 0.7 |
| Investment | 2.7 | 3.9 | 1.0 | 0.9 |

All Statistics Computed on Logged, HP-filtered Data

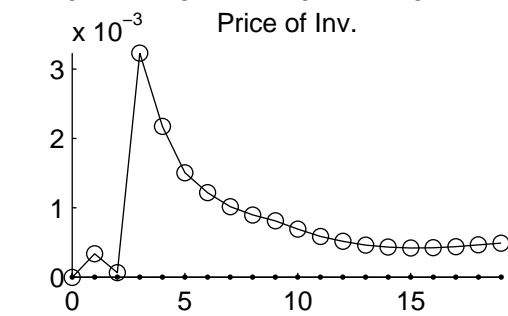
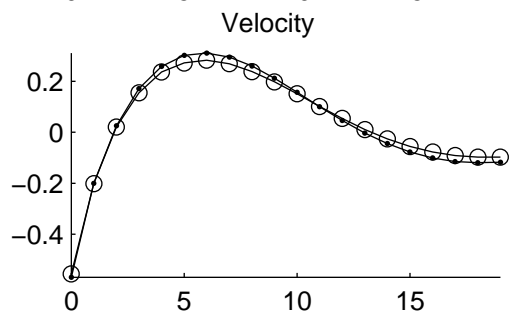
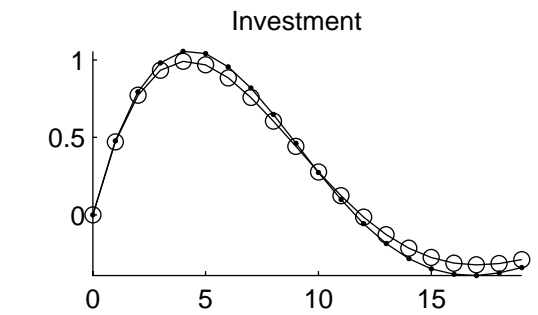
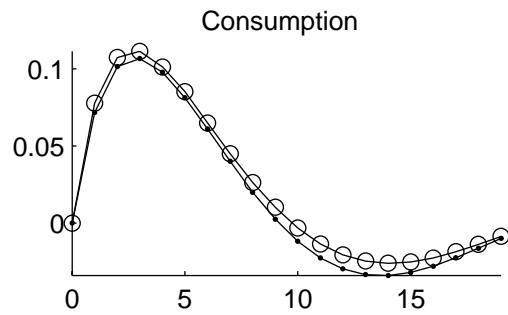
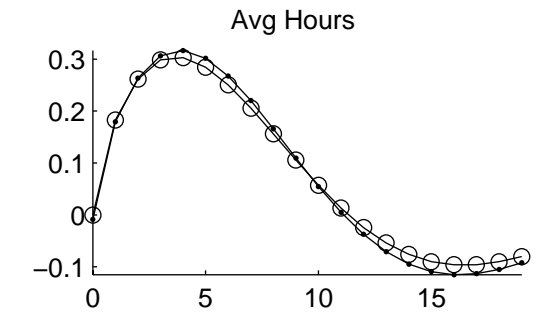
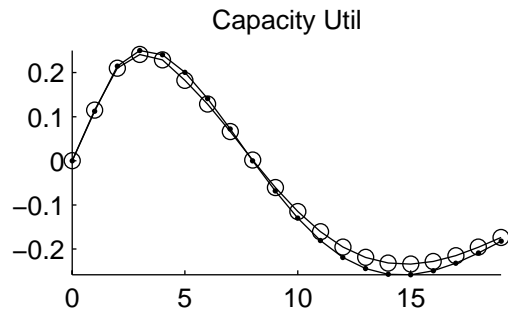
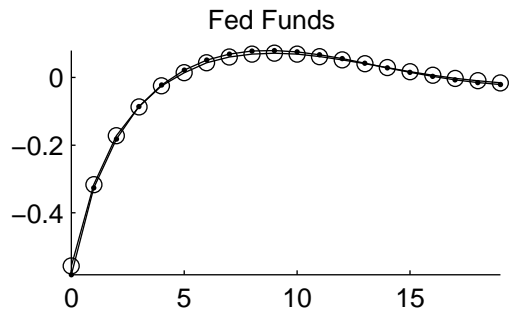
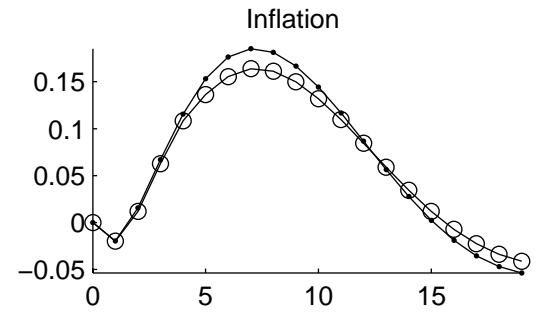
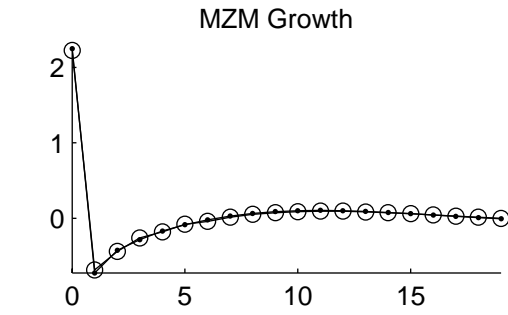
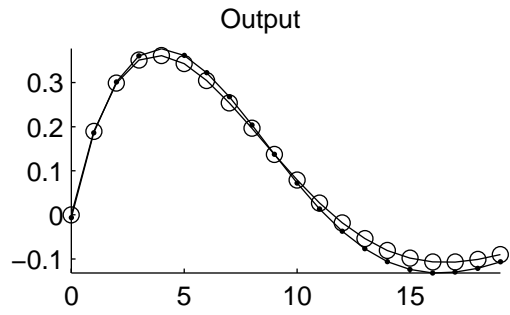
...

- Experiment:
 - Report Impulse Responses of 10 Model Variables to Three Shocks (This is ‘Truth’, for Purposes of Experiment)
 - Simulate Artificial Data From Model
 - Estimate a 10-Variable, 4-Lag VAR (with a little measurement error, for non-singularity) in Artificial Data.
 - Use Long-Run Identifying Restrictions and Monetary Policy Shock Identification to Estimate Impulse Response Functions
 - * Large Sample
 - * Small Sample

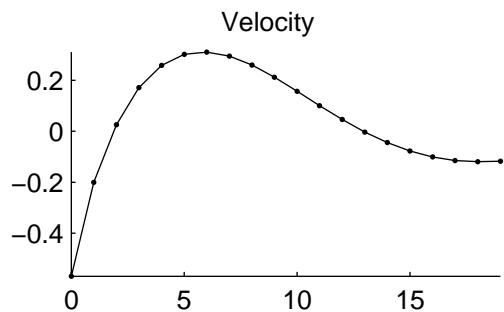
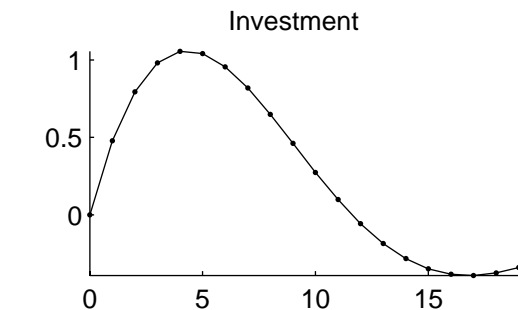
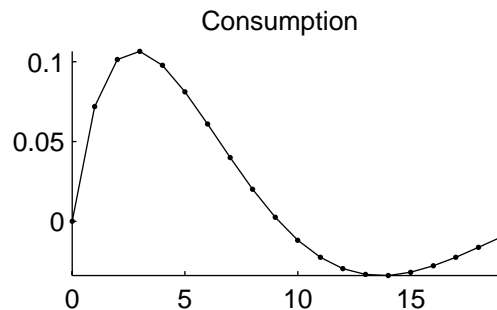
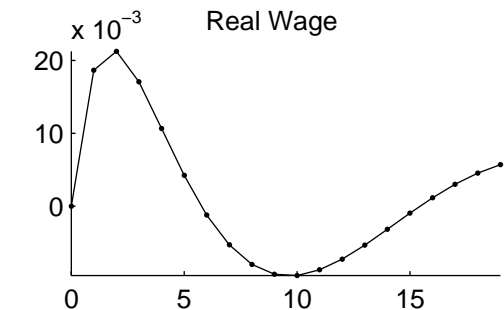
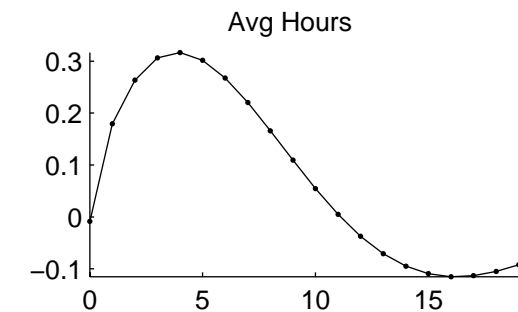
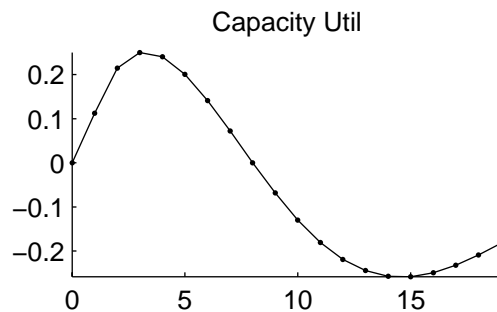
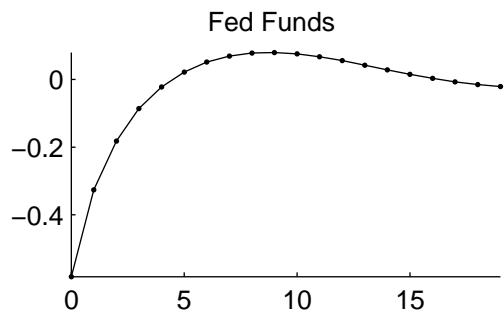
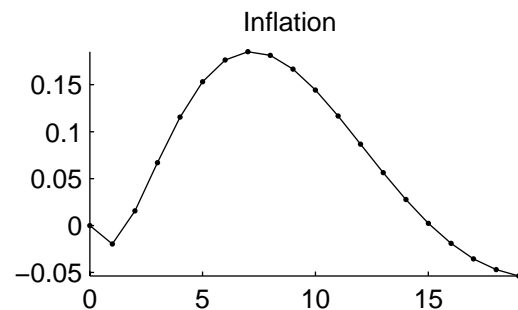
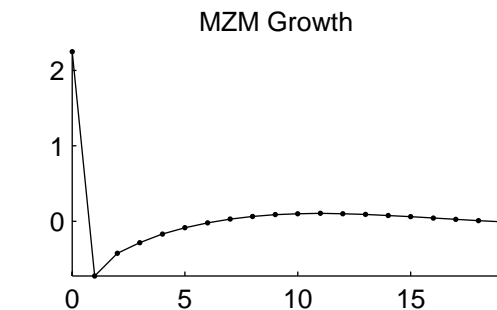
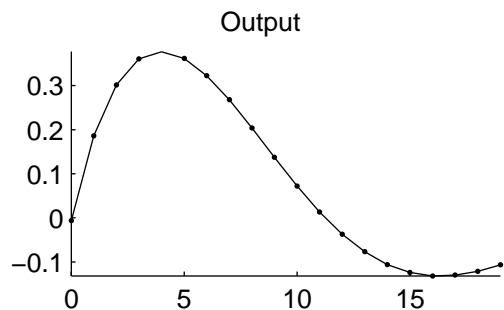
Dynamic responses to a monetary policy shock: true model



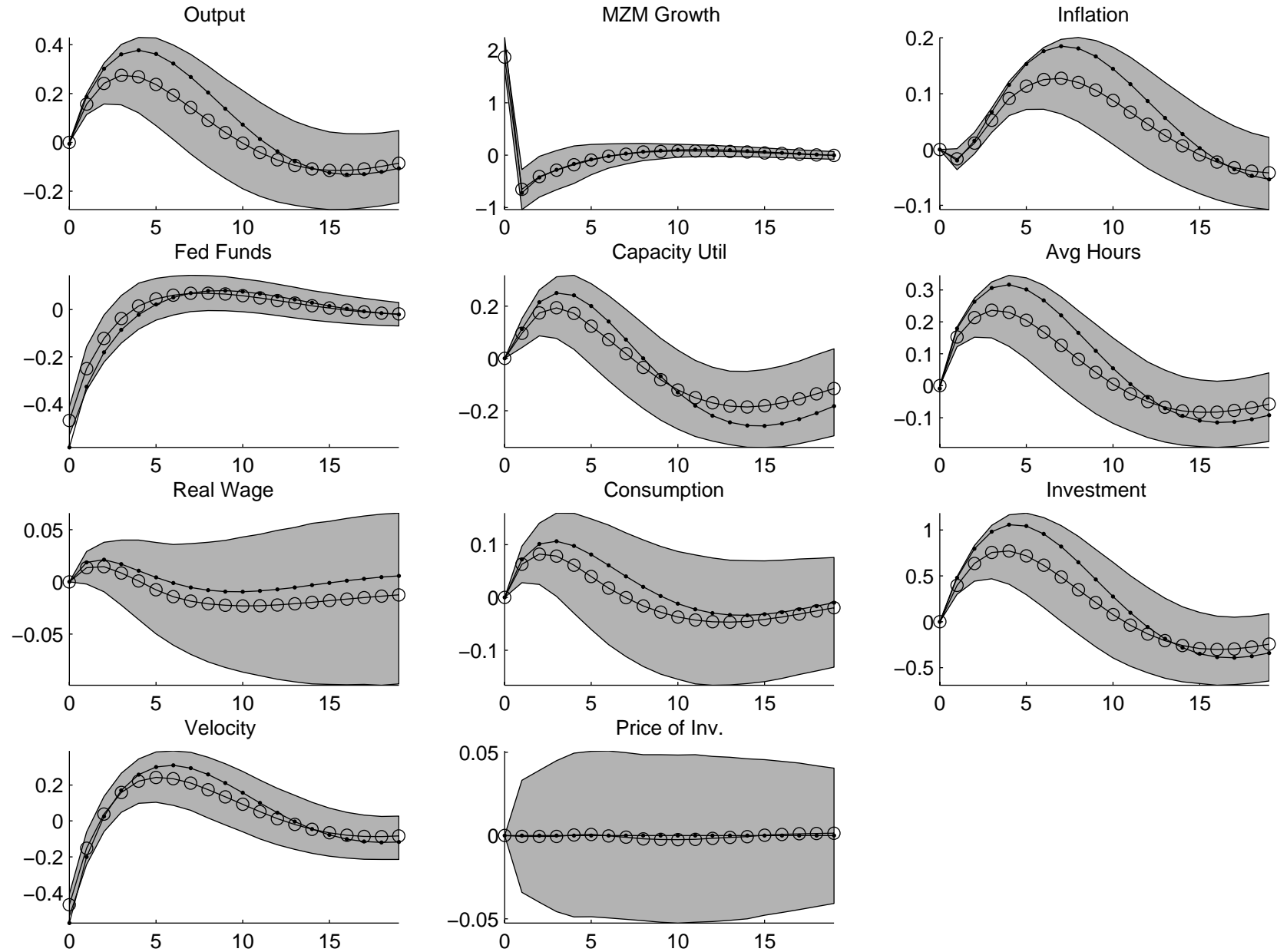
Dynamic responses to a monetary policy shock: true model (.) vs. VAR on simulated data (o)



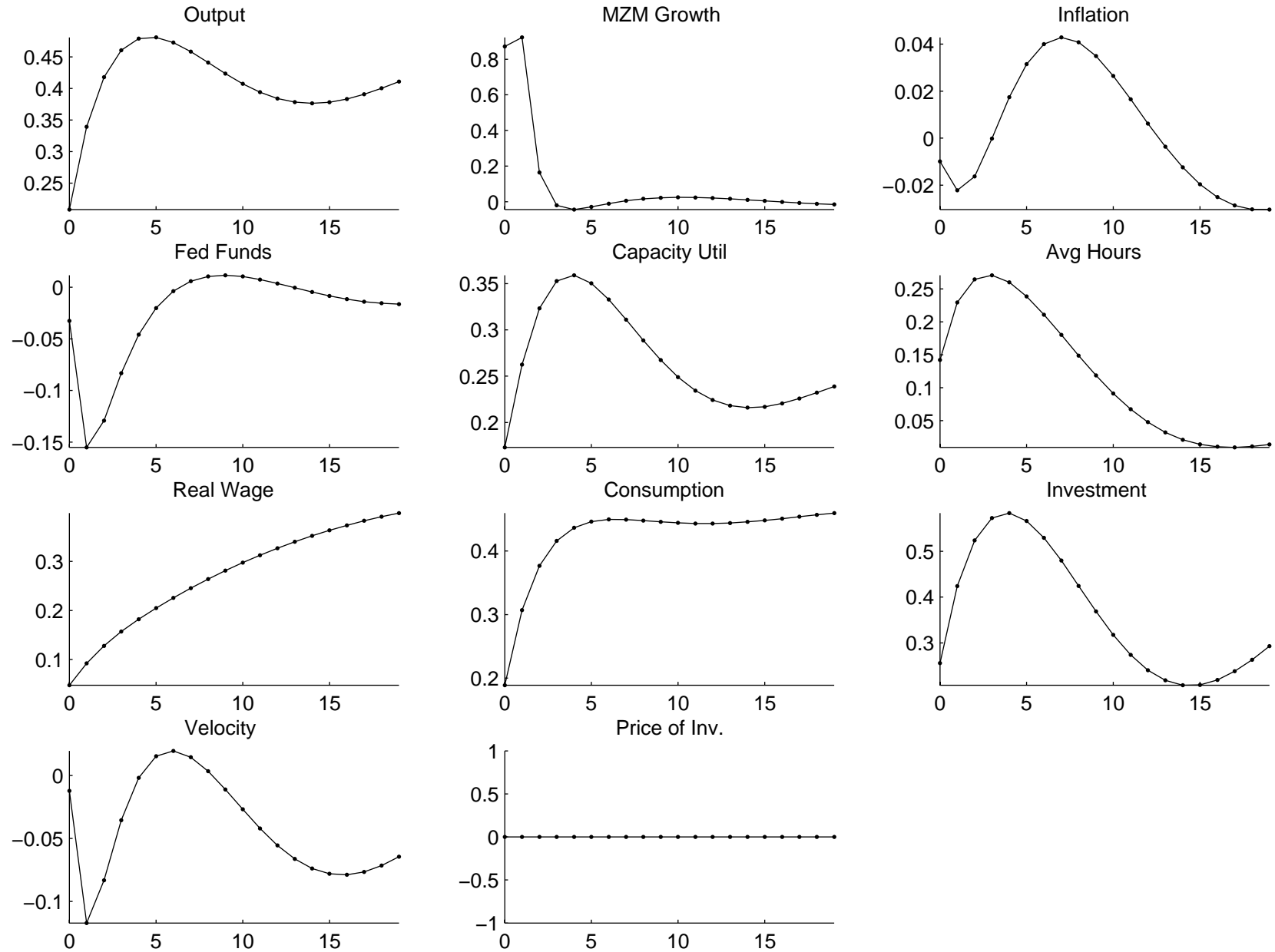
Dynamic responses to a monetary policy shock: true model



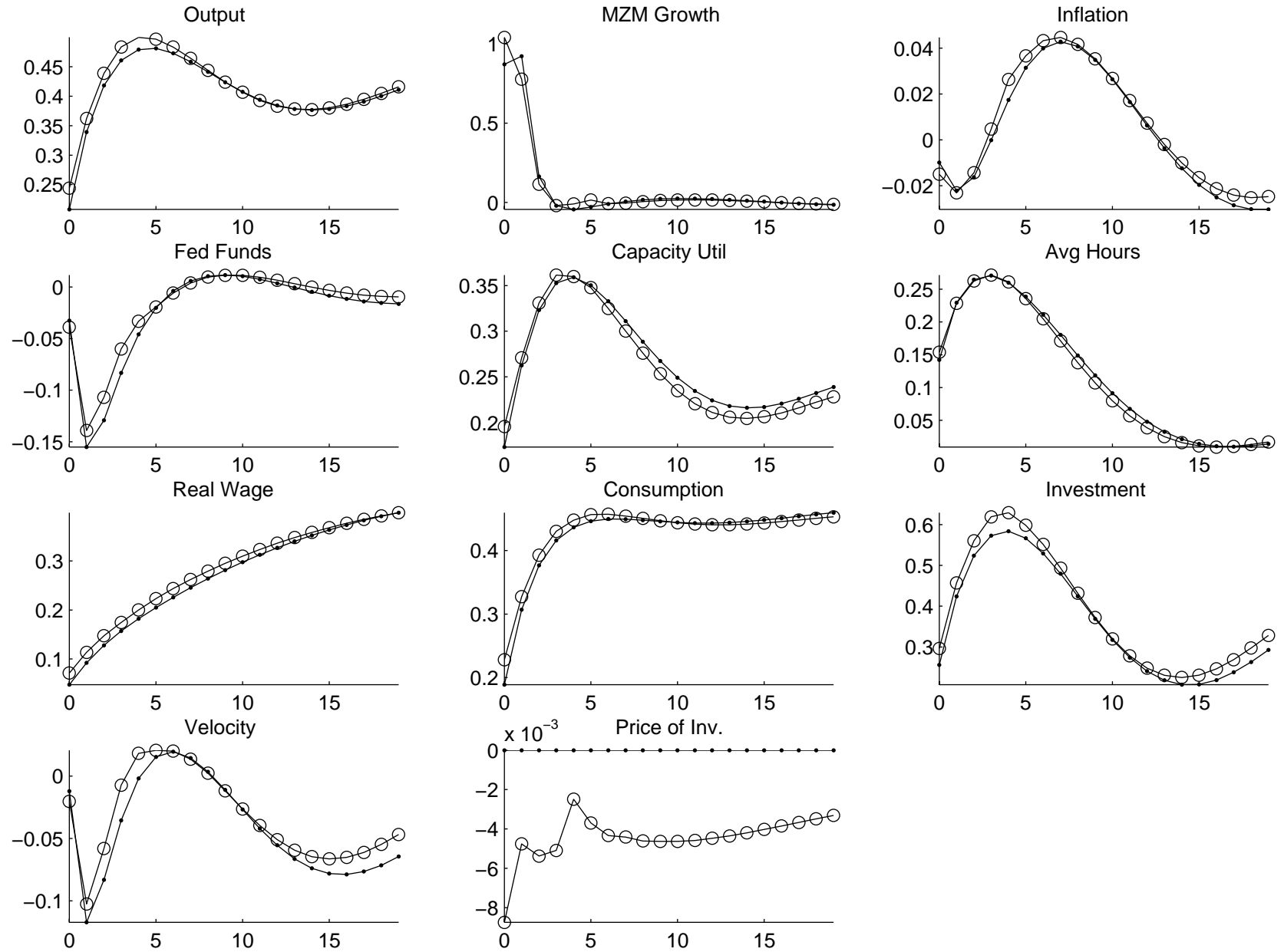
Dynamic responses to a monetary policy shock: true model (.) vs. VAR on simulated data (o)



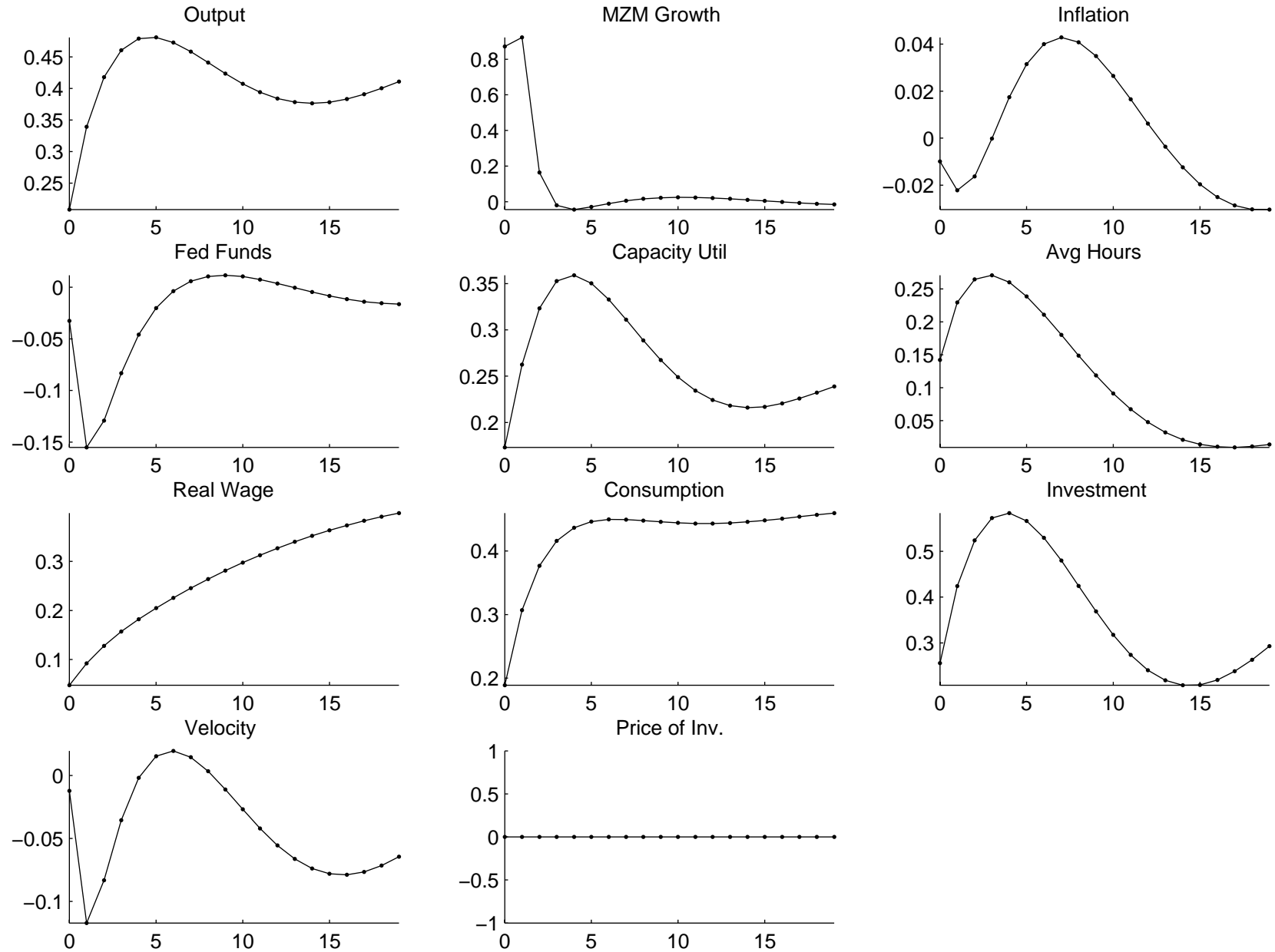
Dynamic responses to a neutral technology shock: true model



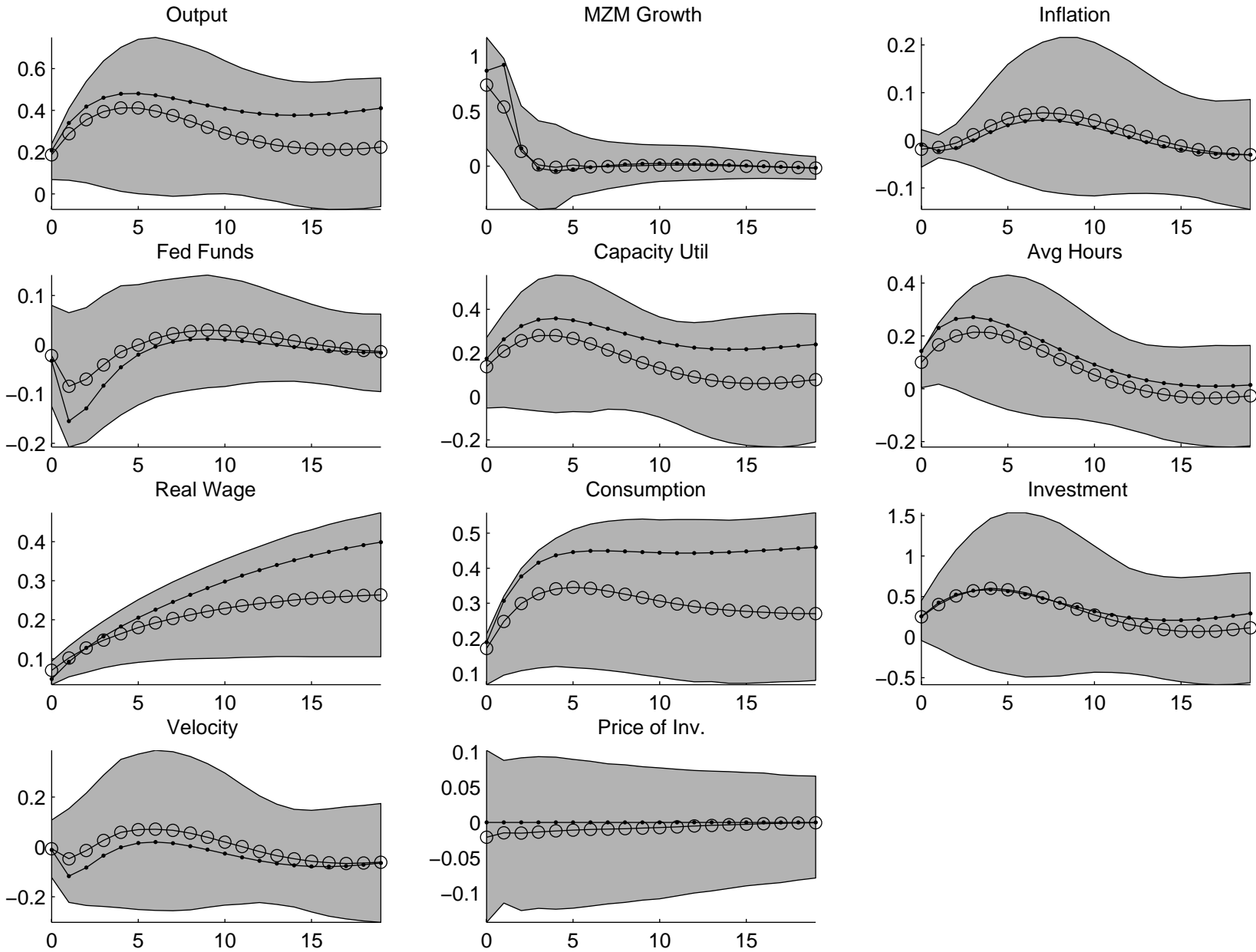
Dynamic responses to a neutral technology shock: true model (.) vs. VAR on simulated data (o)



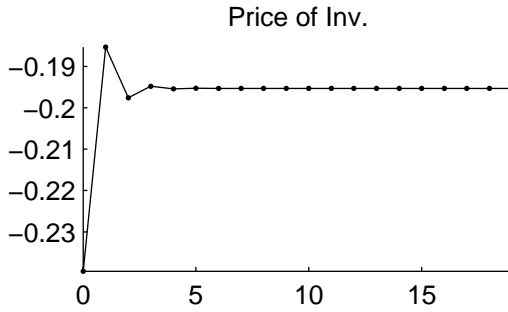
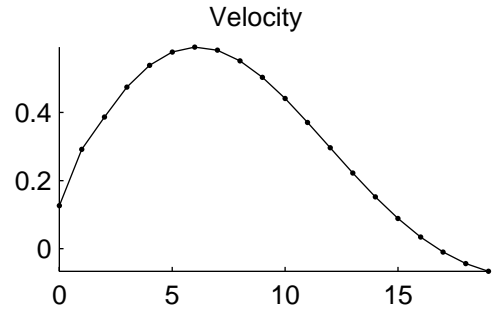
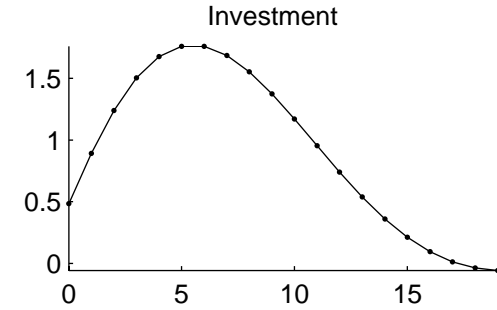
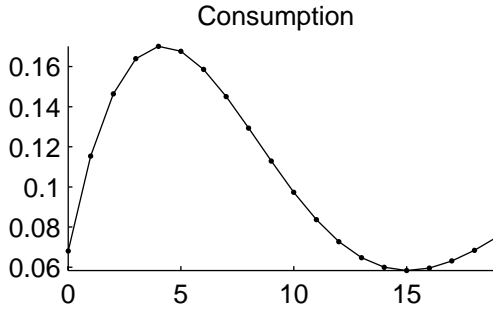
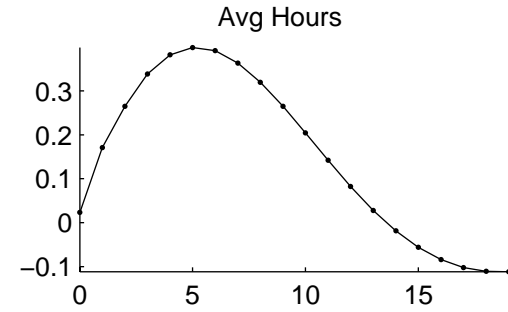
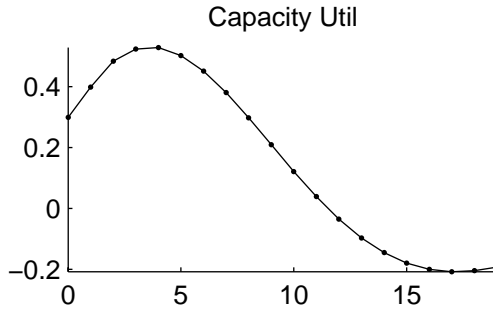
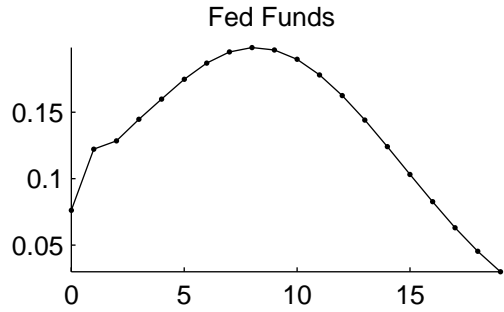
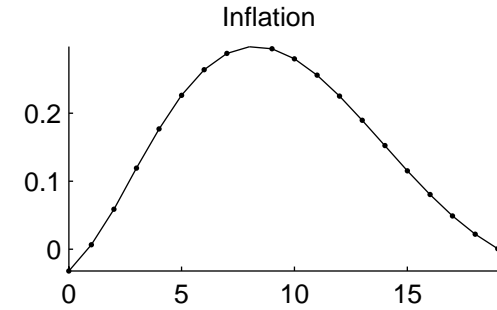
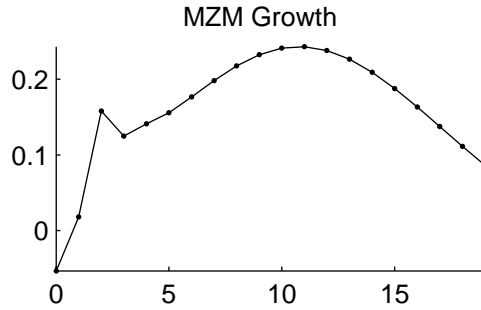
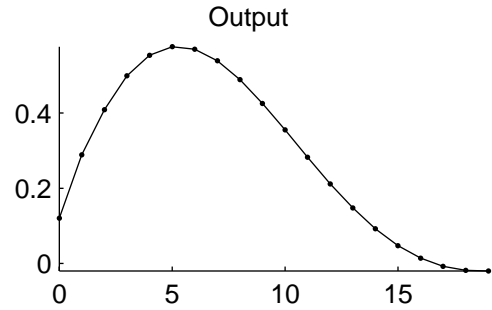
Dynamic responses to a neutral technology shock: true model



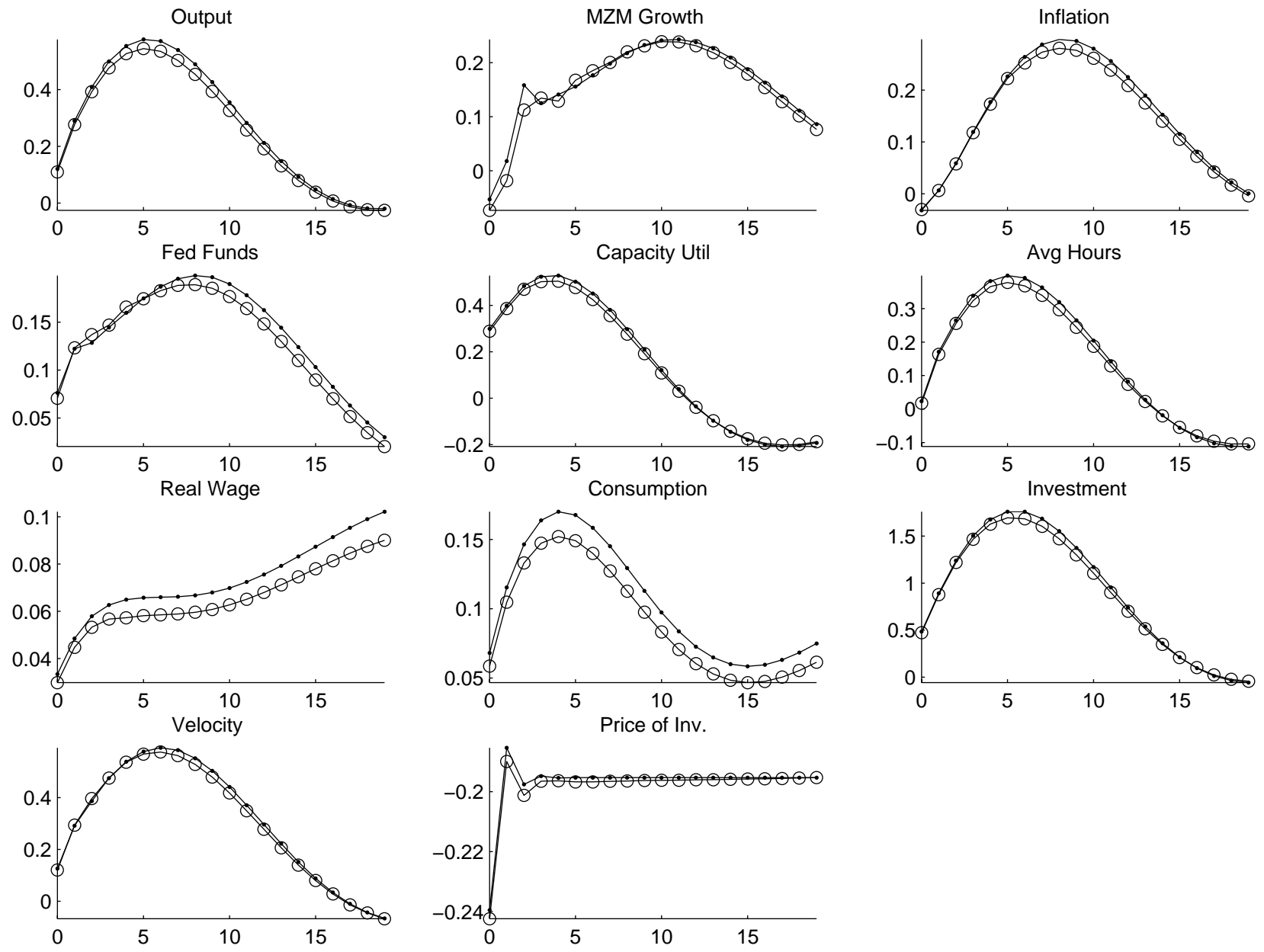
Dynamic responses to a neutral technology shock: true model (.) vs. VAR on simulated data (o)



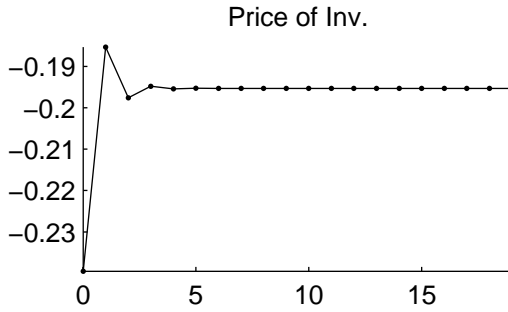
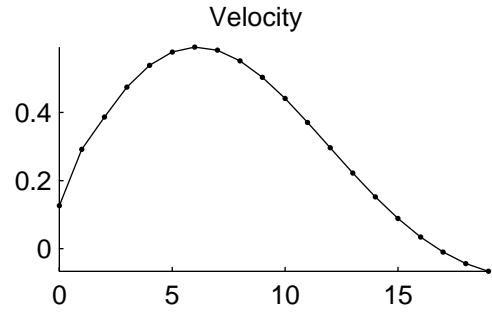
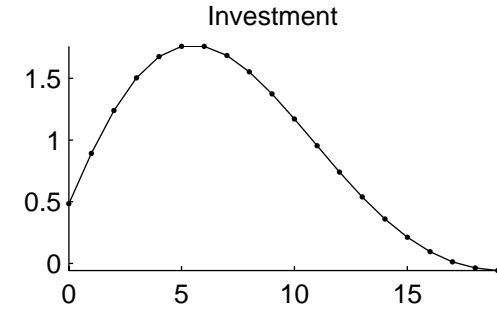
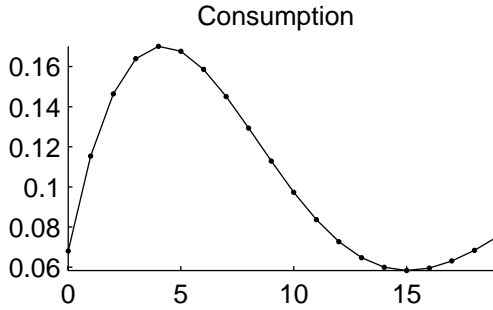
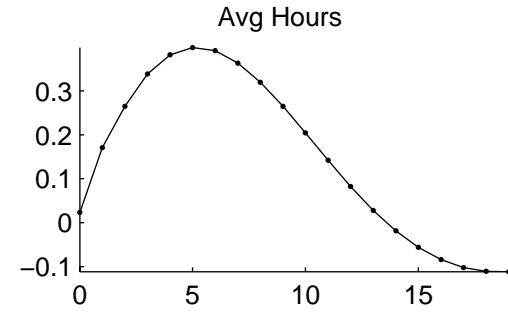
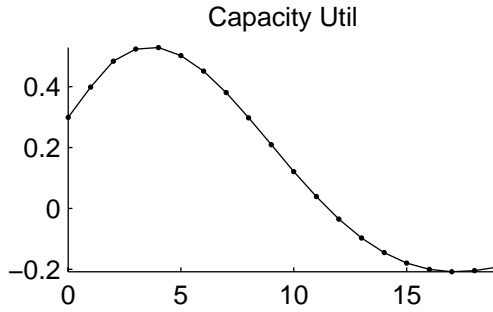
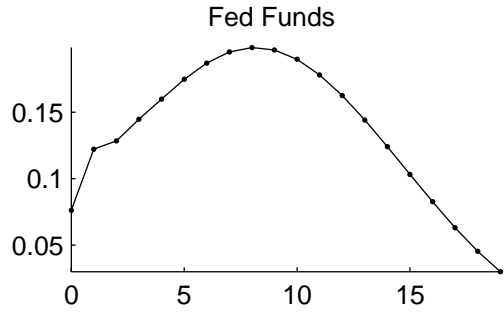
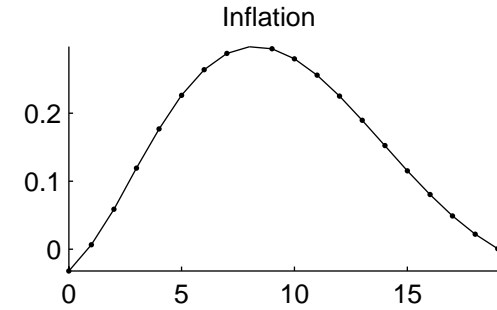
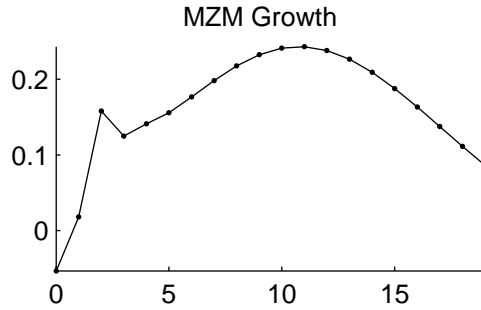
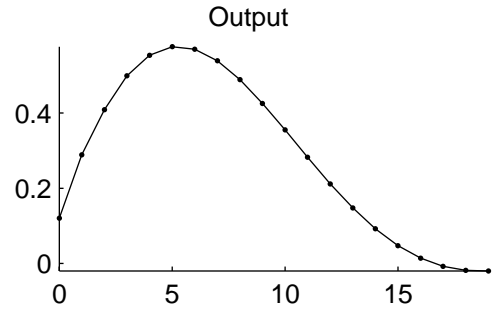
Dynamic responses to an embodied technology shock: true model



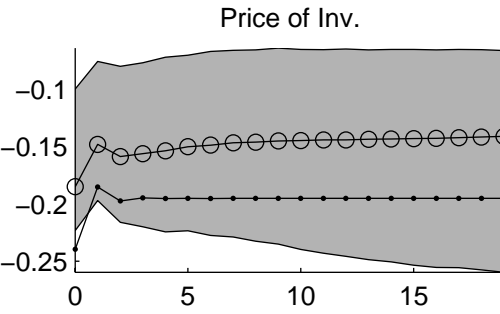
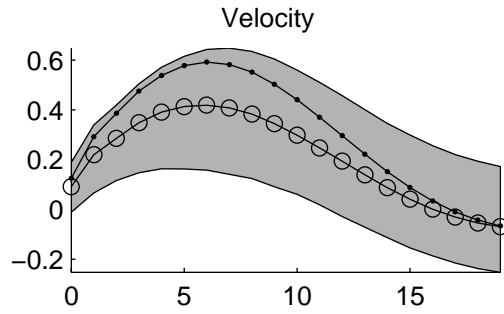
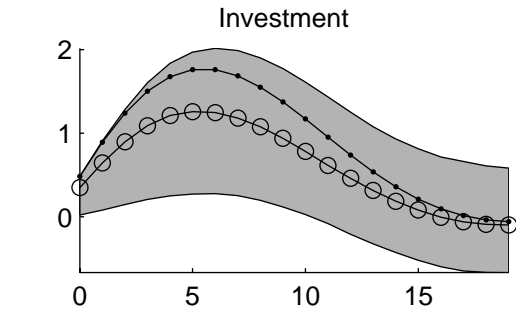
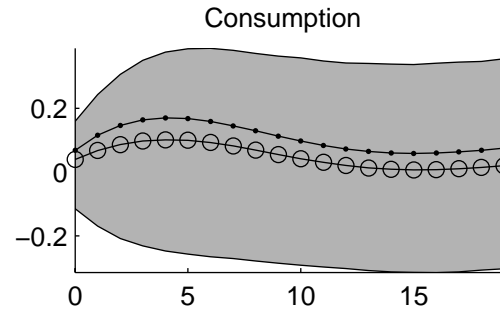
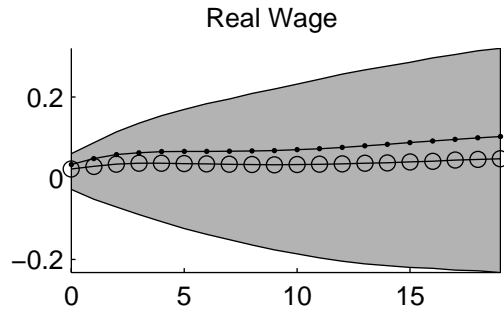
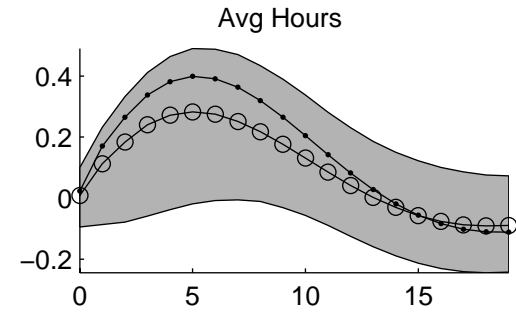
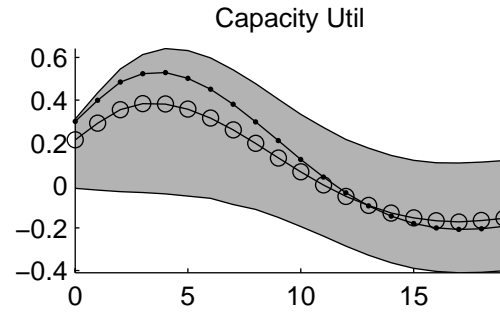
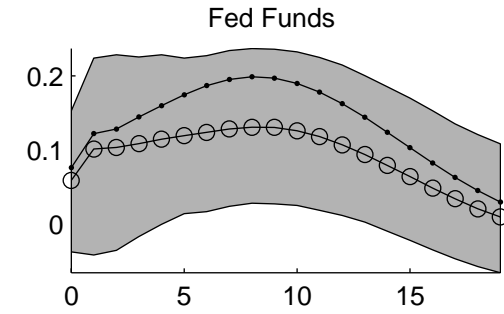
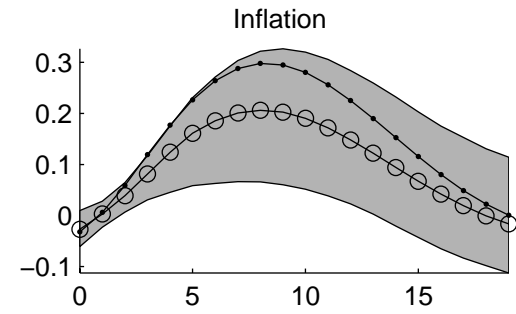
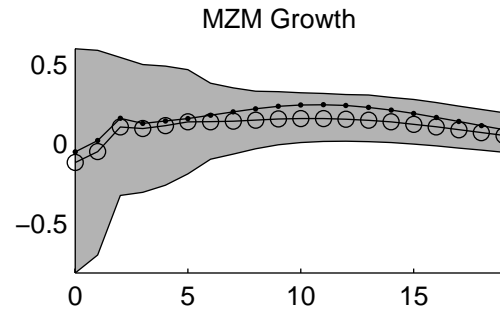
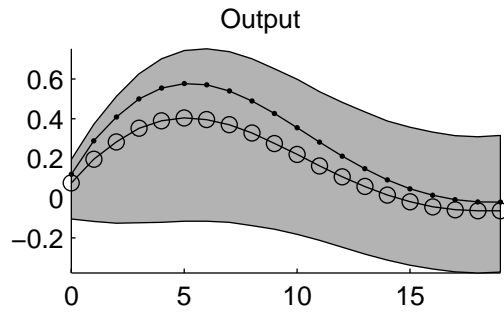
Dynamic responses to an embodied technology shock: true model (.) vs. VAR on simulated data (o)



Dynamic responses to an embodied technology shock: true model



Dynamic responses to an embodied technology shock: true model (.) vs. VAR on simulated data (o)



...

- In the Example, Performance of VAR Seems Adequate:
 - Little Large or Small Sample Bias,
 - Sampling Variation, Though Large in Some Cases, Not Out of Line With Standard Estimates of Sampling Uncertainty.
- Perhaps Different Result From CKM Has to do With Presence of Many More Variables in VAR.

...

Concluding Remarks

- CKM Hope to Induce Researchers to Stop Working With Identified VARs.

...

Concluding Remarks

- CKM Hope to Induce Researchers to Stop Working With Identified VARs.
- Their Case is Built Around Three Examples.

...

Concluding Remarks

- CKM Hope to Induce Researchers to Stop Working With Identified VARs.
- Their Case is Built Around Three Examples.
- Two Examples Show How a Researcher Who Makes a Wrong Assumption Will Reach the Wrong Conclusion.
 - This Does *Not* Imply that Actual Researchers Have Made Wrong Assumptions or Reached the Wrong Conclusions.
 - In Practice, There are Things the Researchers Can Do To Guard Against Mistakes.

...

Concluding Remarks

- CKM Hope to Induce Researchers to Stop Working With Identified VARs.
- Their Case is Built Around Three Examples.
- Two Examples Show How a Researcher Who Makes a Wrong Assumption Will Reach the Wrong Conclusion.
 - This Does *Not* Imply that Actual Researchers Have Made Wrong Assumptions or Reached the Wrong Conclusions.
 - In Practice, There are Things the Researchers Can Do To Guard Against Mistakes.
- One Example is Presented in Which Impulse Responses From VARs May be Distorted, Even Without Wrong Assumptions.

...

Concluding Remarks

- CKM Hope to Induce Researchers to Stop Working With Identified VARs.
- Their Case is Built Around Three Examples.
- Two Examples Show How a Researcher Who Makes a Wrong Assumption Will Reach the Wrong Conclusion.
 - This Does *Not* Imply that Actual Researchers Have Made Wrong Assumptions or Reached the Wrong Conclusions.
 - In Practice, There are Things the Researchers Can Do To Guard Against Mistakes.
- One Example is Presented in Which Impulse Responses From VARs May be Distorted, Even Without Wrong Assumptions.
 - Not Clear that this Poses a Problem in Practice.
 - I Presented an Example Drawn from a Research Study in Which the Problem Is Not Present.

...

- No Need to Throw Identified VAR's Out of Economist's Tool Kit.

...

- No Need to Throw Identified VAR's Out of Economist's Tool Kit.
 - Identified VAR's Are Known to Have Problems (Cooley-Dwyer, Faust-Leeper, Erceg-Guerrieri-Gust, Hansen-Sargent, Lippi-Reichlin).
 - * But, there are Ways to Guard Against the Problems.

...

- No Need to Throw Identified VAR's Out of Economist's Tool Kit.
 - Identified VAR's Are Known to Have Problems (Cooley-Dwyer, Faust-Leeper, Erceg-Guerrieri-Gust, Hansen-Sargent, Lippi-Reichlin).
 - * But, there are Ways to Guard Against the Problems.
 - * Just Because Something Isn't *Perfect* Doesn't Mean it Is Not Good, or Useful.

...

- No Need to Throw Identified VAR's Out of Economist's Tool Kit.
 - Identified VAR's Are Known to Have Problems (Cooley-Dwyer, Faust-Leeper, Erceg-Guerrieri-Gust, Hansen-Sargent, Lippi-Reichlin).
 - * But, there are Ways to Guard Against the Problems.
 - * Just Because Something Isn't *Perfect* Doesn't Mean it Is Not Good, or Useful.
 - VARs Have Proved Useful in Guiding the Construction and Estimation of Dynamic Economic Models.
 - As With Any Econometric Tool, It Should Be Used With Caution.

...

- No Need to Throw Identified VAR's Out of Economist's Tool Kit.
 - Identified VAR's Are Known to Have Problems (Cooley-Dwyer, Faust-Leeper, Erceg-Guerrieri-Gust, Hansen-Sargent, Lippi-Reichlin).
 - * But, there are Ways to Guard Against the Problems.
 - * Just Because Something Isn't *Perfect* Doesn't Mean it Is Not Good, or Useful.
 - VARs Have Proved Useful in Guiding the Construction and Estimation of Dynamic Economic Models.
 - As With Any Econometric Tool, It Should Be Used With Caution.
- The Best Proof of the Value of a Methodology Lies In Whether It Helps Us Learn About the Data.

...

- No Need to Throw Identified VAR's Out of Economist's Tool Kit.
 - Identified VAR's Are Known to Have Problems (Cooley-Dwyer, Faust-Leeper, Erceg-Guerrieri-Gust, Hansen-Sargent, Lippi-Reichlin).
 - * But, there are Ways to Guard Against the Problems.
 - * Just Because Something Isn't *Perfect* Doesn't Mean it Is Not Good, or Useful.
 - VARs Have Proved Useful in Guiding the Construction and Estimation of Dynamic Economic Models.
 - As With Any Econometric Tool, It Should Be Used With Caution.
- The Best Proof of the Value of a Methodology Lies In Whether It Helps Us Learn About the Data.
 - Tomorrow, We Will Present a Paper Which May Convince You that Identified VARs are Useful For Constructing Dynamic Business Cycle Model.