

MONTE CARLO SIMULATIONS OF GLOBULAR CLUSTER EVOLUTION. IV. DIRECT INTEGRATION OF STRONG INTERACTIONS

JOHN M. FREGEAU¹ & FREDERIC A. RASIO²

Department of Physics and Astronomy, Northwestern University, Evanston, IL 60208

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ABSTRACT

We study the dynamical evolution of globular clusters containing populations of primordial binaries, using our newly updated Monte Carlo cluster evolution code with the inclusion of direct integration of binary scattering interactions. We describe the modifications we have made to the code, as well as improvements we have made to the core Monte Carlo method. We present several test calculations to verify the validity of the new code, and perform many comparisons with previous analytical and numerical work in the literature. We simulate the evolution of a large grid of models, with a wide range of initial cluster profiles, and with binary fractions ranging from 0 to 1, and compare with observations of Galactic globular clusters. We find that our code yields excellent agreement with direct N -body simulations of clusters with primordial binaries, but yields some results that differ significantly from other approximate methods. Our results for the structural parameters of clusters during the binary-burning phase are outside the range of parameters for observed clusters, implying that either clusters are born significantly more or less centrally concentrated than has been previously considered, or that there are additional physical processes beyond two-body relaxation and binary interactions that affect the structural characteristics of clusters.

Subject headings: globular clusters: general — methods: numerical — stellar dynamics

1. INTRODUCTION

Observations (e.g., Cote et al. 1996; Bellazzini et al. 2002b; Rubenstein & Bailyn 1997; Cool & Bolton 2002; Bellazzini et al. 2002a), in combination with recent theoretical work (Ivanova et al. 2005), suggest that although the currently observed binary fractions in the cores of globular clusters may be small ($\lesssim 10\%$), the initial cluster binary fraction may have been significantly larger ($\gtrsim 50\%$). As has been understood theoretically for some time, primordial binaries in star clusters generally act as an energy source (through super-elastic scattering encounters), producing energy in the core and postponing deep core collapse in a quasi-steady state “binary-burning” phase. This is analogous to the long-lived main-sequence in stars, in which hydrogen is burned to prevent collapse. An initial binary fraction of a few percent is enough to postpone deep core collapse for many initial relaxation times (see Fregeau et al. 2003, for discussion and references). Note that for clusters with a very wide initial mass spectrum, primordial binaries do not always postpone core collapse (see, e.g., Zwart et al. 2006). In addition to playing a large part in the global evolution of a star cluster, dynamical interactions of binaries also strongly affect the formation and evolution of stellar and binary exotica, which include low-mass X-ray binaries, recycled pulsars, cataclysmic variables, and blue stragglers (Hut et al. 1991; Sigurdsson & Phinney 1995; Davies & Hansen 1998; Rasio et al. 2000; Ivanova et al. 2005).

Similarly to dynamical binary interactions, physical stellar collisions (both direct star–star collisions, and those mediated by resonant binary interactions) also play an important role in the evolution of globular cluster populations. Stellar collisions are thought to be one of the

two primary mechanisms by which blue stragglers are created in dense star clusters (e.g., Mapelli et al. 2004). A runaway sequence of stellar collisions of massive main sequence stars early in the lifetime of a dense cluster may yield a very massive star ($\gtrsim 10^3 M_{\odot}$), which may then become an intermediate mass black hole (see, e.g., Gürkan et al. 2006, for discussion and references).

The complete picture of star cluster evolution can be rather complicated, as it includes, in addition to the two physical processes just mentioned, single star evolution, binary star evolution, and tidal stripping due to the field of the Galaxy. Even if one ignores these additional processes, modeling a dense stellar cluster with primordial binaries still presents a formidable computational challenge. There are at least two reasons for this: 1) dynamical interactions of binaries—which are typically resonant, lasting for many orbits—must be resolved on their natural timescale, which is orders of magnitude shorter than the cluster relaxation time, and 2) primordial binaries extend the life of a cluster. Although the GRAPE series of special-purpose computers is steadily increasing in performance, direct N -body simulation of the evolution of clusters with more than a few percent binaries and a moderate number of stars ($\sim 10^5$) is still quite computationally expensive, with computational timescales on the order of months. Faster, more approximate methods, such as the anisotropic gas model or direct solution of the Fokker-Planck equation, suffer from the difficulty inherent in incorporating physics beyond two-body relaxation, such as stellar evolution or binary interactions, in these methods. The Monte Carlo method bridges the gap between these two computational extremes, since it allows for the relatively facile inclusion of additional layers of physics, provides a star-by-star description of a cluster, and is computationally inexpensive.

In previous studies using approximate methods like

¹ fregeau@alum.mit.edu

² rasio@northwestern.edu

Monte Carlo or Fokker-Planck, binary interactions had generally been treated using recipes culled from the results of large numbers of numerical scattering experiments. (The work of Giersz & Spurzem (2003), which incorporates direct integration of binary interactions, is one notable exception.) The recipes are typically known only for equal-mass binary interactions, thus prohibiting the use of a cluster mass function. Thus in order to model realistic clusters, which contain a wide range of masses, one must numerically integrate each binary interaction in order to resolve it properly. We have now incorporated into our Monte Carlo code a dynamical integrator to exactly integrate dynamical interactions of binaries, allowing us to evolve clusters with mass spectra, and perform more realistic comparisons with direct N -body calculations.

In this paper we describe our new code, perform several tests to ensure its validity, and perform a large set of simulations of clusters with primordial binaries, which we compare with previous results in the literature and with observations of Galactic globular clusters. Section 2 describes our new code in detail, including the additional physical processes we have added (numerical integration of binary scattering interactions, and star–star physical collisions), as well as the improvements we have made to the core Monte Carlo method. Section 3 presents a few example results, verifies the gravothermal nature of the core oscillations we find in our simulations, and compares our results with semi-analytical theory and previous numerical calculations. Section 4 describes the trends evident in the grid of cluster models we simulated, and compares our results with observations. Finally, in section 5 we summarize and conclude.

2. METHOD

Here we describe in detail our implementation of the Monte Carlo numerical method for simulating the evolution of dense star clusters. It incorporates many physical processes of relevance in dense star clusters, including two-body relaxation, direct physical stellar collisions, and dynamical interactions of binaries. Each of these physical processes is treated sufficiently accurately so as to allow for a rather wide mass spectrum (e.g., $M_{\max}/M_{\min} \sim 10^3$ for a Salpeter mass function). For now we neglect stellar evolution (both single and binary), but plan to include it in our code in the near future. Those readers uninterested in the technical details of our numerical method can safely skip ahead to the next section.

2.1. Units

Before describing our method in detail, we discuss a necessary formality. We use the standard N -body system of units (Heggie & Mathieu 1986; Heggie & Hut 2003). For reasons of convenience, we use two units of time in our code. In addition to the standard N -body unit of time (which is roughly the crossing time), we use the relaxation time³. Thus our full (over-specified) system

³ Using the relaxation time as the time unit removes N from any equations of relaxational evolution.

of units is given by the standard formulae:

$$U_m = M_0 \quad (1)$$

$$U_l = \frac{GM_0^2}{-4E_0} \quad (2)$$

$$U_t = \frac{GM_0^{5/2}}{(-4E_0)^{3/2}} \quad (3)$$

$$U_{t_{\text{rel}}} = \frac{N_0}{\ln \gamma N_0} U_t, \quad (4)$$

where M_0 is the initial total mass of the cluster, E_0 is the initial total energy of the cluster, N_0 is the initial number of stars, and γN_0 is the Coulomb logarithm. The quantity γ is a function of the initial structure of the cluster, and is only needed when converting time in code units to physical units. Thus it does not need to be specified for purely relaxation calculations, which can be quoted in units of the relaxation time, but it does need to be specified for calculations which include additional physics, like physical collisions and binary interactions. For our simulations we set γ via comparisons with N -body results (where available), as discussed later.

2.2. Standard Definitions

It is often useful to be explicit about how certain derived measurable quantities are calculated. For the half-mass relaxation time we adopt the standard definition (Spitzer & Hart 1971):

$$t_{\text{rh}} = \frac{0.138N}{\ln(\gamma N)} \left(\frac{r_h^3}{GM} \right)^{1/2}, \quad (5)$$

where N is the number of bound cluster objects (single star or binary), r_h is the radius containing half the mass of the cluster, and M is the total cluster mass. Most plots presented in this paper use as time unit the initial half-mass relaxation time, i.e. t_{rh} evaluated at the start of the simulation. For the core radius we adopt the standard definition (Spitzer 1987):

$$r_c = \left(\frac{3\sigma_0^2}{4\pi G \rho_0} \right)^{1/2}, \quad (6)$$

where σ_0 is the central three-dimensional velocity dispersion (calculated in the code via a number-weighted average), and ρ_0 is the central mass density. Note that the results we compare with below from Heggie et al. (2006) adopt a slightly different definition for the core radius. They use a density weighted average (Casertano & Hut 1985), which has been shown to yield a value for the core radius that is roughly 20% smaller than the standard definition (Trenti et al. 2006).

2.3. Two-Body Relaxation

Two-body relaxation is the primary physical process responsible for the diffusion of energy in a star cluster, and thus for its global evolution (Heggie & Hut 2003). We use the Hénon orbit-averaged Monte Carlo method to simulate two-body relaxation (Hénon 1971). For a detailed description of the basic method we employ, see Joshi et al. (2000). In summary, a timestep in the code consists of the following:

1. Using each star’s radial position r and mass m , the potential $\Phi(r)$ is calculated under the assumption of spherical symmetry (each star is represented by an infinitesimally thin spherical shell).
2. Each pair of stars neighboring in radius undergoes a hyperbolic “super”-encounter, with scattering angle chosen so as to represent the cumulative effect on each star of many long-range, small-angle two-body scattering encounters with all other stars in the system.
3. Using the new radial velocity v_r and tangential velocity v_t , the new specific energy E and angular momentum J of each star is calculated (using $\Phi(r)$ from step 1).
4. A new position and corresponding velocity is chosen for each star by picking a point on its orbit randomly, sampled in accordance with the amount of time spent at each radial position (i.e., weighted by $1/v_r$).

We have made two improvements to the fundamental method which were necessary to accurately treat star clusters with wide mass spectra, and for the stability of the long-term evolutions needed for clusters with primordial binaries.

The first improvement is a rather simple one that provides for self-consistency in step 4 above. Solving for the new position of a star along its orbit appears to be a straightforward matter: using the potential calculated in step 1, one writes down the energy equation for the orbit, $E = \Phi(r) + J^2/2r^2 + \frac{1}{2}v_r^2$, solves for the pericenter and apocenter, then samples the radial position with a weighting inversely proportional to v_r . However, the potential calculated in step 1 includes the contribution from the star whose orbit we are trying to solve. In other words, the star on its orbit feels the gravitational effect of itself at its old position. This inconsistency is ignored in the standard Monte Carlo method (Hénon 1971; Joshi et al. 2000), although it is corrected in the new Monte Carlo code of Freitag & Benz (2001). Neglecting this inconsistency for the case of equal-mass clusters produces a minimal effect on the overall evolution, slightly postponing core collapse, and leading to a steady drift in the total system energy. However, when one considers clusters with even modestly wide mass spectra ($\sim 0.1\text{--}10 M_\odot$), the errors are much less benign. Since the most massive stars in the mass spectrum contribute proportionately more to the cluster potential, it is the calculation of their orbits that is most inaccurate. In our simulations we have seen that as the mass spectrum is widened, the core collapse time gets progressively longer than what would be expected—from direct N -body results and the Monte Carlo calculations of Freitag et al. (2006b)—until it is prevented completely. In other words, this inconsistency acts as a spurious energy source, postponing core collapse.

Correcting the inconsistency in the potential is straightforward. We simply add a correction term to the potential when solving for a star’s orbit. For star j with mass m_j , originally at position r_j when the potential was

last calculated, the correction term is

$$\Phi_s(r) = \begin{cases} \frac{Gm_j}{r} & r \geq r_j \\ \frac{Gm_j}{r_j} & r < r_j \end{cases}. \quad (7)$$

In principle, for total consistency, one could also add the self-gravity of the star, $-Gm_j/2r$, since it is treated as a spherical shell. However, we find that adding such a term leads to unphysical behavior for clusters with wide mass spectra when the orbit of one of the more massive stars lies within the innermost few stars (and thus the approximation of spherical symmetry breaks down), the result being that the star acts as an energy source, ultimately preventing core collapse. For narrow mass functions, the addition of the self-gravity term has no noticeable effect on the evolution, as found by Freitag & Benz (2001). Note that for the results presented in Freitag et al. (2006b) and Freitag et al. (2006a), which consider core collapse for wide mass spectra, the self-gravity term is not included (Freitag 2005, private communication).

The second improvement to the code concerns energy conservation and the long-term stability of the code. From the description of a timestep above, it is clear that the potential used to find the new positions of stars in their orbits (in step 4) lags behind by a timestep. The result is a steady drift in the total system energy. This can be compensated for by a technique that considers the mechanical work done by the potential (since it is changing with time) on each star in the system, and uses it to more accurately calculate the velocities at the new position on the orbit (see Stodolkiewicz 1982, for details). Briefly, in this method the new specific kinetic energy of each star at its updated position in step 4, $\frac{1}{2}v_{\text{new}}^2$, is augmented by a term that corresponds to the mechanical work done by the potential on the star, due to the fact that the potential is changing with time. The tangential component of the new velocity is set according to angular momentum conservation as $v_{t,\text{new}} = J/r_{\text{new}}$, where J is evaluated in step 3. This is the same way in which it is set in the standard Monte Carlo method. The radial velocity is then simply $v_{r,\text{new}} = (v_{\text{new}}^2 - v_{t,\text{new}}^2)^{1/2}$. Note the asymmetry in which the components of the new velocity are set. Clearly only the radial component of the velocity takes into account the mechanical work done by the potential. Thus it can happen that $v_{\text{new}}^2 < v_{t,\text{new}}^2$, yielding a nonsensical result for $v_{r,\text{new}}$, in which case ad hoc prescriptions must be used, sometimes leading to spurious results. We use a modified version of this method in which we simply preserve the ratio $v_{r,\text{new}}/v_{t,\text{new}}$ as predicted by the standard Monte Carlo method and scale the velocities so that $v_{r,\text{new}}^2 + v_{t,\text{new}}^2 = v_{\text{new}}^2$. This technique appears to violate angular momentum conservation for individual orbits, but since the Monte Carlo method assumes spherical symmetry, the total angular momentum of the system remains statistically consistent with zero. Our modification to the method of Stodolkiewicz (1982) yields results for clusters with mass spectra that are more consistent with direct N -body simulations, and the simulations of Freitag et al. (2006b). Moreover, the method provides for improved energy conservation throughout long cluster runs, typically conserving energy to within a part in $\sim 10^3$ over tens of half-mass relaxation times.

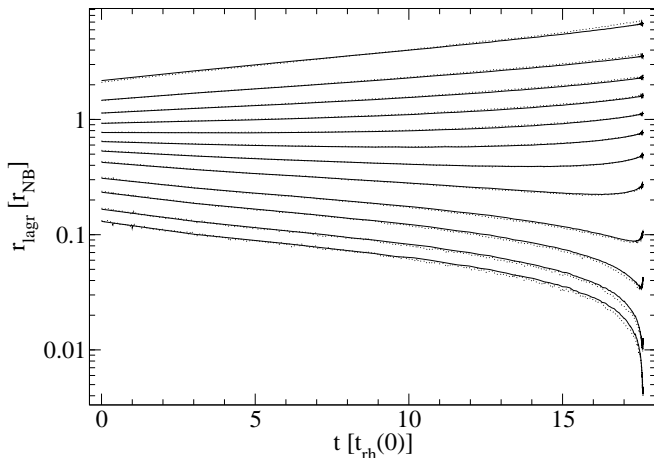


FIG. 1.— Evolution of the Lagrange radii for a single-component Plummer model (model T1 in Table 1) calculated with our Monte Carlo code (solid lines), and compared with a direct N -body calculation (dotted lines). The Lagrange radii shown enclose a fixed fraction of the total bound cluster mass of (from bottom to top) 0.01, 0.02, 0.05, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, and 0.9. Our model had 5×10^5 stars, while the N -body model had 65536. The time unit in the N -body model was converted from dynamical times to relaxation times using a value of $\gamma = 0.10$ in the Coulomb logarithm.

To demonstrate the validity of our improved technique for two-body relaxation, we have compared calculations of clusters subject only to relaxational evolution with the results from other numerical techniques. Fig. 1 shows the evolution of the Lagrange radii for a single-component Plummer model (model T1 in Table 1) calculated with our Monte Carlo code (solid lines), and compared with a direct N -body code (dotted lines). The agreement between the Monte Carlo method and direct N -body is clearly excellent for this model. The core collapse time of $t_{cc}/t_{rh} = 17.6$ is in good agreement with most other approximate techniques, as can be seen in the table of Freitag & Benz (2001). For the comparison we had to convert the dynamical time units of the N -body model to relaxation time units, using a value of $\gamma = 0.10$ in the Coulomb logarithm. This value is in good agreement with theoretical arguments (Hénon 1975) and other numerical calculations (Giersz & Heggie 1994; Freitag & Benz 2001).

We have also looked at the evolution of the density profile, as shown in Fig. 2, initially and at the time of core collapse. A power-law density profile with $\rho \propto r^{-2.3}$ clearly develops at late times. The power-law index of -2.3 is in good agreement not only with the results of other Monte Carlo calculations (Freitag & Benz 2001), but also with N -body simulations which give an index of -2.26 (Baumgardt et al. 2003), and self-similar analytical Fokker-Planck calculations and coarse dynamic renormalization calculations which give a power-law index of -2.23 (Szell et al. 2005).

Next we considered the evolution of a model with a moderately wide mass spectrum. Fig. 3 compares the evolution of the Lagrange radii calculated with our code with a direct N -body calculation of a Plummer model with a Kroupa initial mass function from $0.1 M_\odot$ to $10 M_\odot$ (model T2). Our model used $N = 10^6$ stars while

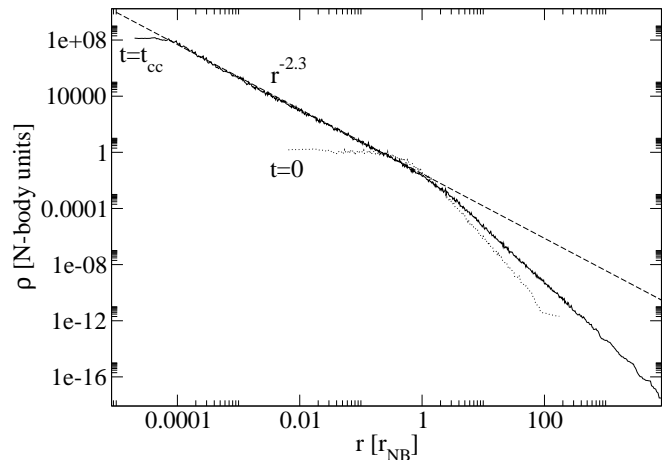


FIG. 2.— Three-dimensional mass density profiles of model T1 initially and at core collapse. At core collapse the cluster develops a large power-law profile with exponent -2.3 , in good agreement with other analytical and numerical calculations.

the N -body model used $N = 131072$. Again, the agreement is quite good, at least to within the level of noise in the N -body simulation. The N -body model does not undergo deep collapse, since it appears to form a three-body binary that stalls core collapse. (Note that three-body binary formation is not included in our Monte Carlo code.) A value of $\gamma = 0.05$ in the Coulomb logarithm was used to convert between dynamical time units and relaxation time units. Fig. 4 shows the evolution of the average mass within the Lagrange radii, compared with N -body. It appears that for the innermost Lagrange radii (which have the largest average mass), our Monte Carlo method predicts an evolution that lags behind the N -body method, but eventually catches up at late times. Note that the Monte Carlo method of Freitag et al. (2006b) suffers from the same malady, albeit to a lesser degree.

Finally, we considered the evolution of a model with a very wide mass spectrum. Fig. 5 compares the Lagrange radii with N -body for a Plummer model with a Salpeter initial mass function from $0.2 M_\odot$ to $120 M_\odot$ (model T3). Our model used $N = 1.25 \times 10^6$ stars while the N -body model used $N = 262144$. Again, the agreement is quite good, although the N -body model is rather noisy, especially at late times. Here a value of $\gamma = 0.01$ in the Coulomb logarithm was used, which is in good agreement with the comparison between Monte Carlo and N -body of Freitag et al. (2006b). Fig. 6 shows the evolution of the average mass within the Lagrange radii for the same model. Here our model lags even further behind the N -body model at early times, but again catches up at late times. Note that the degree to which our model disagrees with N -body appears to be very similar to that of the Monte Carlo code of Freitag et al. (2006b).

In general, for two-body relaxation, the agreement of our code with the results of direct N -body calculations, as well as those of other approximate techniques, has been improved greatly by the two major code modifications we have described here.

2.4. Strong Interactions

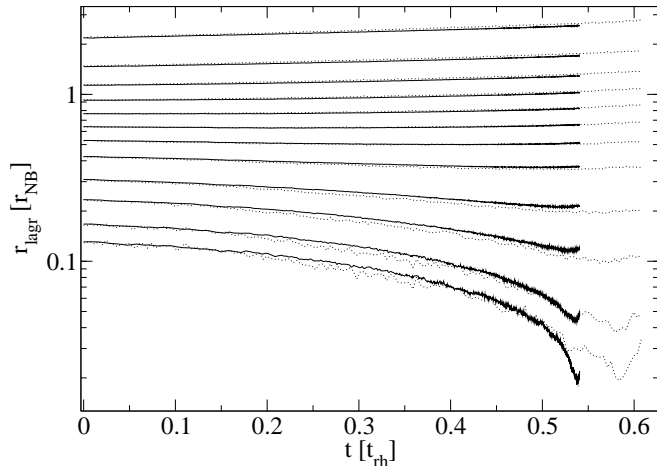


FIG. 3.— Evolution of the Lagrange radii for a Plummer model with a Kroupa initial mass function from $0.1 M_{\odot}$ to $10 M_{\odot}$ (model T2) calculated with our Monte Carlo code (solid lines), and compared with direct N -body (dotted lines). The Lagrange radii shown enclose a fixed fraction of the total bound cluster mass of (from bottom to top) 0.01, 0.02, 0.05, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, and 0.9. Our model had 10^6 stars, while the N -body model had 131072. The conversion between dynamical time units and relaxation time units required a value of $\gamma = 0.05$ in the Coulomb logarithm.

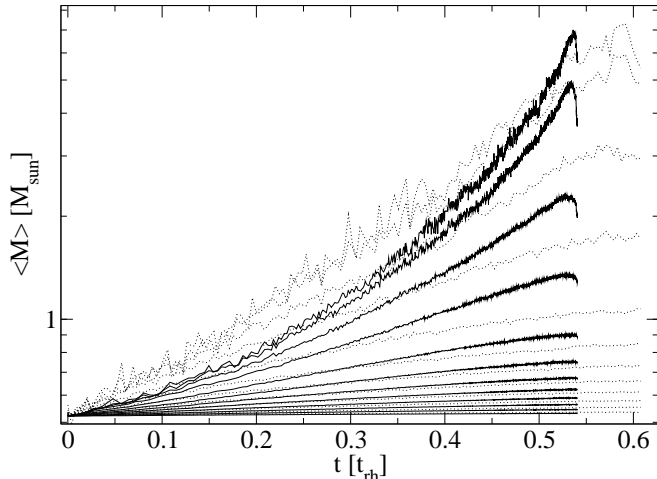


FIG. 4.— Evolution of the average mass within each Lagrange radius for model T2 calculated with our code (solid lines), compared with N -body (dotted lines). The values of the Lagrange radii are the same as in the previous figure.

Owing to the flexibility of the Monte Carlo method, it is reasonably simple to layer additional physics on top of the basic two-body relaxation technique. This includes those two-body processes which we call “strong interactions,” including single–single physical collisions, dynamical binary interactions (between two binaries or a binary and a single star), and large-angle scattering. At present we have included single–single collisions and binary interactions. For both we sample the interactions using the technique of Freitag & Benz (2002) (also discussed in Giersz 2001). In brief, this amounts to evaluating the quantity

$$P_{\text{strong}}^{(12)} = n_* v_{\infty} S_{\text{strong}}^{(12)} \delta t \quad (8)$$

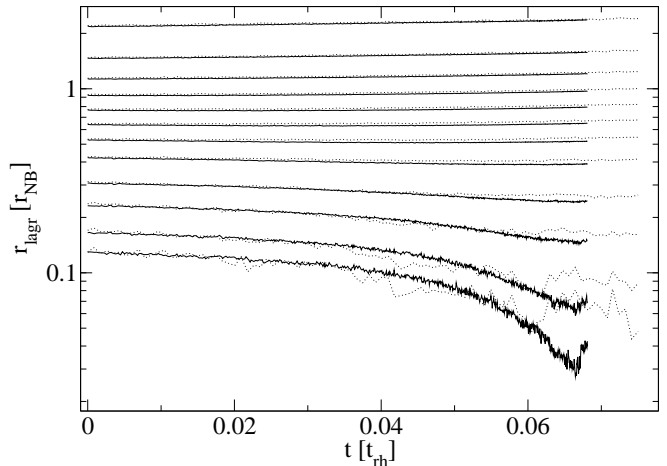


FIG. 5.— The evolution of the Lagrange radii for a Plummer model with a Salpeter initial mass function from $0.2 M_{\odot}$ to $120 M_{\odot}$ (model T3) calculated with our Monte Carlo code (solid lines), compared with N -body (dotted lines). The Lagrange radii shown enclose a fixed fraction of the total bound cluster mass of (from bottom to top) 0.01, 0.02, 0.05, 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, and 0.9. Our model had 1.25×10^6 stars, while the N -body model had 262144. A value of $\gamma = 0.01$ in the Coulomb logarithm was used to convert time units.

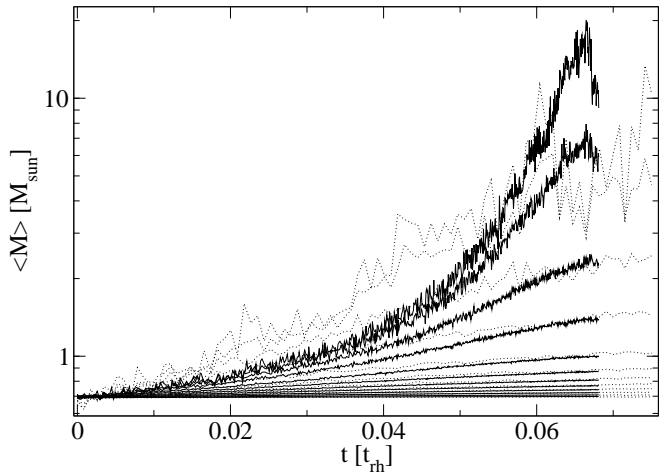


FIG. 6.— Evolution of the average mass within each Lagrange radius for model T3 calculated with our code (solid lines), compared with N -body (dotted lines). The values of the Lagrange radii are the same as in the previous figure.

for each pair of stars that neighbor in radial position, where $P_{\text{strong}}^{(12)}$ is the probability for a strong interaction to occur, n_* is the local number density of stars (binary or single), v_{∞} is the relative velocity of the pair at infinity, $S_{\text{strong}}^{(12)}$ is the cross section for the strong interaction, δt is the timestep, and the notation “(12)” signifies that the first star is of type “1” while the second is of type “2”. This quantity is a standard “ $n\sigma v$ ” estimate for the interaction probability between stars of type “1” and “2”. However, it is the total number density of stars n_* that appears in the equation, and not n_1 or n_2 . As shown in Freitag & Benz (2002), when used in this context, eq. (8) yields the correct sampling of the collision rate, since the act of choosing the neighboring star samples

the local density of that type of star (for details, please see section 2.4.2 of Freitag & Benz 2002).

At each timestep, for each pair of stars, the value of $P_{\text{strong}}^{(12)}$ is evaluated (P_{bb} for binary–binary interactions, P_{bs} for binary–single, and P_{coll} for single–single collisions) and compared with a uniform deviate in $X \in [0, 1]$. If $X < P_{\text{strong}}$ the strong interaction is performed, otherwise the pair undergoes two-body relaxation.

Note that $S_{\text{strong}}^{(12)}$ can be written in a very general way in terms of the maximum value of the classical pericenter distance between the pair in their hyperbolic orbit which yields a strong interaction. In this case it is

$$S_{\text{strong}}^{(12)} = \pi b_{\text{max}}^2 = \pi r_p^2 \left(1 + \frac{2GM}{r_p v_\infty^2} \right), \quad (9)$$

where b_{max} is the impact parameter leading to a classical pericenter distance of r_p , and M is the total mass of the pair. We will use this expression below.

2.4.1. Single–Single Collisions

Although the simulations we present in this paper do not include physical stellar collisions (we defer such simulations to a future paper), we still include here for the sake of completeness a description of the implementation of collisions in the code. For direct physical collisions between main-sequence stars, the outcome can vary greatly depending on v_∞ . For relative speeds greater than the escape speed from the surface of the star ($v_\infty \gtrsim v_{\text{esc}} \approx 500$ km/s for a typical solar-mass MS star), which can occur in galactic nuclei, a collision typically results in a large fraction of the total mass lost from the system (see, e.g., Freitag & Benz 2005, and references therein). For $v_\infty \lesssim v_{\text{esc}}$, which is satisfied for globular clusters, the result is typically a clean merger, with a negligible amount of mass lost from the system (e.g., Benz & Hills 1987; Lombardi et al. 2002). Since we are concerned with the latter case in this paper, we treat physical single–single collisions using the sticky sphere approximation, which assumes that if the radii of stars touch during a strong interaction they merge with no mass loss. The sticky sphere approximation, when used for stellar collisions of main-sequence stars in models of low velocity dispersion clusters, has been shown to agree extremely well with the results of more detailed calculations incorporating the results of SPH simulations (Freitag et al. 2006b,a). With this approximation, the cross section for collisions is given by eq. (9) with $r_p = R_1 + R_2$:

$$S_{\text{coll}}^{(12)} = \pi(R_1 + R_2)^2 \left(1 + \frac{2GM}{(R_1 + R_2)v_\infty^2} \right), \quad (10)$$

where M is the total mass of the two stars.

We have tested that our code correctly samples single–single star collisions so as to reproduce the correct collision rate. For a Plummer model, the collision rate can be solved for analytically, yielding (Freitag & Benz 2002):

$$\frac{dN_{\text{coll}}(R)}{dtd \ln R} = 54 \left(\frac{3MG}{2\pi R_P^3} \right)^{1/2} u^3 (1 + u^2)^{-21/4} \times \Theta_0^{-2} \left[1 + \Theta_0(1 + u^2)^{1/2} \right], \quad (11)$$

where M is the total cluster mass, R is the radial position in the cluster, R_P is the scale radius of the Plummer model ($R_P = 3\pi/16$ in N -body units), $u = R/R_P$,

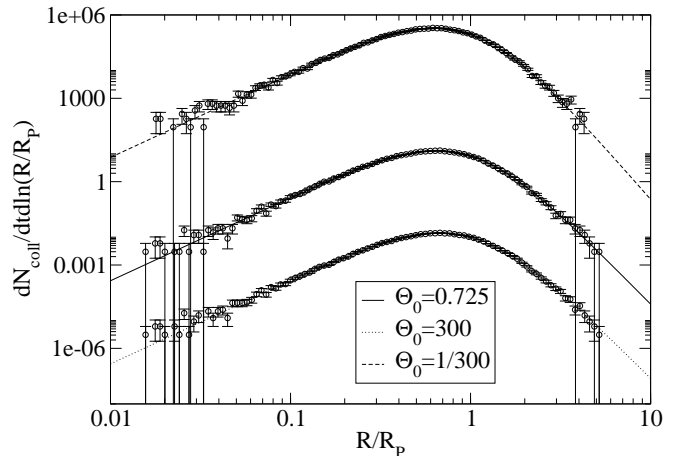


FIG. 7.— Comparison of the numerically sampled single–single star collision rate (circles) with the analytical result (lines) for a single-mass Plummer model with $N = 10^6$ stars, for three different values of the Safronov number ($\Theta_0 = 1/300, 0.725$, and 300).

and Θ_0 is the Safronov number (Binney & Tremaine 1987). Based on our sticky sphere collision prescription, the Safronov number can be written simply as $\Theta_0 = 3R_P/NR_*$, where N is the number of stars in the cluster, and R_* is a stellar radius. We have extracted the collision rate from a simulation of an unevolving Plummer model (relaxation turned off) composed of $N = 10^6$ equal-mass stars. Instead of performing collisions, we simply recorded them. Fig. 7 shows a comparison of the numerically extracted rate (circles) with the analytical rate (lines), for three different values of Θ_0 ($1/300, 0.725$, and 300). The agreement is excellent for all values of Θ_0 .

2.4.2. Binary Interactions

All dynamical binary interactions (binary–binary and binary–single) are directly numerically integrated with *Fewbody*, an efficient computational toolkit for evolving small- N dynamical systems (Fregeau et al. 2004). *Fewbody* was designed specifically for performing dynamical scattering interactions, and thus it is well-suited for our purposes. See Fregeau et al. (2004) for a detailed description of the code. Note that *Fewbody* also properly treats physical stellar collisions during binary interactions, using the same criterion for a collision as used in the Monte Carlo code for single–single collisions.

For sampling binary interactions, we use the same technique described above for single–single collisions, but with the cross sections appropriate to binary interactions. For binary–binary interactions, the cross section is given by eq. (9) with $r_p = X_{\text{bb}}(a_0 + a_1)$, where a_i are the binary semimajor axes, and X_{bb} is a parameter. X_{bb} must be set large enough so that all binary–binary interactions of interest are followed. Since in this paper we are concerned mainly with the global evolution of clusters, we need only follow most of the energy-generating binary interactions. In principle, one could make X_{bb} arbitrarily large, so as to capture *all* potentially interesting interactions. The result would be many more weakly-interacting fly-by interactions, which incur an infinitesimal computational cost due to *Fewbody*'s efficient integration techniques. However, due to the way in which

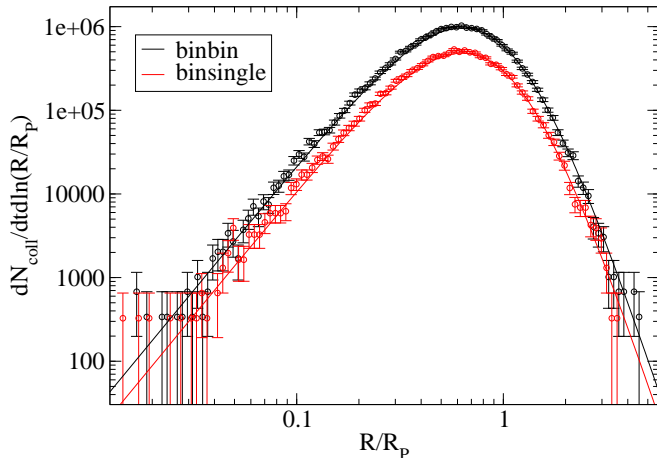


FIG. 8.— Comparison of the numerically sampled binary interaction rates (circles) with the analytical result (lines) for binary–binary interactions (black) and binary–single (red) for a single-mass Plummer model with $N = 10^6$ stars. In this test, binaries had the same mass as single stars. This simplified the analytical calculation of the rate.

the global Monte Carlo timestep is chosen (see below), time would grind to a halt in our code. Clearly, then, setting X_{bb} is a compromise between capturing all binary interactions of interest (larger X_{bb}), and preventing the timestep from becoming unnaturally small (smaller X_{bb}). We use $X_{bb} = 2$ for the results presented in this paper. We find that this value is a good compromise. For binary–single interactions, we take $r_p = X_{bs}a$, where a is the binary semimajor axis, and set $X_{bs} = 2$.

As we did for single–single collisions, we have performed a calculation of an unevolving Plummer model to test that our code correctly samples the binary interaction rates. In this test, a fraction $f_b = 0.5$ of the $N = 10^6$ stars were binaries. The binaries had the same mass as single stars in order to simplify the analytical calculation of the rate. Again, strong interactions were not performed, simply recorded. Since there are two species (binaries and single stars), the interaction rate is given by eq. (11) with an extra factor of f_b for binary–single, and f_b^2 for binary–binary. Fig. 8 shows a comparison of the numerically sampled binary interaction rates (circles) with the analytical result (lines) for binary–binary interactions (black) and binary–single (red). The agreement is excellent.

Once a binary interaction is deemed to occur, the relative velocity at infinity of the pair is taken to be the current relative velocity of the pair in the cluster (with the angle of each particle’s tangential velocity randomized), and the impact parameter, b , of the interaction is chosen uniformly in area out to b_{max} as given in eq. (9). With all parameters of the scattering encounter set, the interaction is numerically integrated with *Fewbody* until an unambiguous outcome is reached. The outcome products of the interaction are then placed back into the cluster with their resultant internal properties (mass, binary semimajor axis, eccentricity, etc.) and external properties (systemic velocity, etc.).

The only exception to this rule is stable hierarchical triples. These stable triples frequently result from

binary–binary interactions (roughly 20% of the time for equal-mass, equal-energy hard binaries; see, e.g., Mikkola 1983). In principle we could keep the triples in the code, and follow their evolution, allowing them to undergo interactions with other single stars, binaries, and triples (*Fewbody* can handle all these cases with ease since it is general in N). However, for simplicity we currently break triples into a binary and a single star. We do this by allowing the outer member of the triple to just barely escape to infinity, with the inner binary shrinking its orbit to conserve energy in the process. For simplicity, both the single star and binary are given the systemic velocity of the original triple.

Finally, we must discuss one more detail. Since the binary interactions performed with *Fewbody* are done in a vacuum—in other words, there are no stars other than the ones in the interaction to prevent members of the small- N system from making arbitrarily large excursions—it happens that some binary interactions leave extremely wide binaries (sometimes as wide as the cluster itself) as their outcome products. Clearly this is an unphysical situation, as no binary should ever become larger than the inter-particle separation in a comparable-mass cluster. We therefore break these pathologically wide binaries at the end of each timestep. Our criterion for breaking the binaries is that they have an orbital velocity that is roughly smaller than the local velocity dispersion, since it is this boundary in phase space and not the hard–soft boundary that determines binary lifetime in a cluster (Fregeau et al. 2006). We break the binaries if the orbital speed of their lightest member is less than $X_{hs}\sigma(R)$, where $\sigma(R)$ is the velocity dispersion at position R in the cluster, and X_{hs} is a parameter which we take to be 0.7. We set $X_{hs} < 1$ as a safety measure, to ensure that no long-lived binaries are erroneously broken.

2.5. Stellar Evolution

For the mass–radius relationship we adopt an approximate piece-wise fit to the more detailed one used by Freitag et al. (2006b) for $Z = 10^{-3}$:

$$R(M) = \begin{cases} 0.1R_{\odot} & M/M_{\odot} \leq 0.1 \\ R_{\odot}(M/M_{\odot}) & 0.1 \leq M/M_{\odot} \leq 1 \\ R_{\odot}(M/M_{\odot})^{0.57} & 1 \leq M/M_{\odot} \leq 120 \\ 1.6R_{\odot}(M/M_{\odot})^{0.47} & M/M_{\odot} \geq 120 \end{cases} \quad (12)$$

The first two pieces (up to $M = 1 M_{\odot}$) are based on Chabrier & Baraffe (2000). The next piece is based on Schaller et al. (1992), and the last is from Bond et al. (1984). The fit is a rough approximation to the more exact relationships given in the references listed, but suffices for our purposes since we use it only for determining limits on the properties of the initial binary population (as described below).

2.6. Timestep Evaluation

The timestep in the code should be chosen small enough to resolve the relevant physics (two-body relaxation, collisions, binary interactions, etc.), but not smaller than necessary. We take the timestep to be the minimum of the characteristic timescales for the different physical processes.

For two-body relaxation, we use the standard expression for the characteristic timescale for two species of

particles undergoing relaxation to deflect each other by an angle θ_{\max} (Freitag & Benz 2001):

$$T_{\text{rel}} = \frac{\theta_{\max}}{\pi/2} \frac{\pi}{32 \ln(\gamma N) G^2 n (M_1 + M_2)^2} v_{\text{rel}}^3, \quad (13)$$

where v_{rel} is the relative speed of the two species, n is the local number density of stars, and M_i are the masses of each species of star. The standard expression for the relaxation time comes from setting $\theta_{\max} = \pi/2$ (Binney & Tremaine 1987). We evaluate eq. (13) by a local sliding average as

$$T_{\text{rel}} = \frac{\theta_{\max}}{\pi/2} \frac{\pi}{32 \ln(\gamma N) G^2 n \langle (M_1 + M_2)^2 \rangle} \langle v_{\text{rel}} \rangle^3, \quad (14)$$

yielding T_{rel} as a function of radial position in the cluster. We take the minimum value of T_{rel} for the calculation of the timestep. The minimum most often occurs at the center of the cluster, where the density is the highest. However, it can sometimes happen for clusters with wide mass spectra that the minimum occurs away from the center, due to a massive star in a sea of lighter stars. We adopt $\theta_{\max} = 1$ for all simulations presented in this paper, which we find to be a good compromise between accuracy and computational speed. The distribution of scattering angles in a typical timestep has a very long tail at large θ , so most super-encounters have a much smaller scattering angle than θ_{\max} .

For strong interactions, we evaluate the timescale for each pair of particles neighboring in radius to undergo a strong interaction, by performing an “ $n\sigma v$ ” estimate. This can be written

$$T_{\text{strong}}^{-1} = \frac{1}{n} \int d^3\mathbf{v}_1 d^3\mathbf{v}_2 f(\mathbf{v}_1) f(\mathbf{v}_2) |\mathbf{v}_2 - \mathbf{v}_1| S_{\text{strong}}, \quad (15)$$

where \mathbf{v}_i is the velocity of star i , and f is the velocity distribution function. Assuming a Maxwellian velocity distribution for stars “1” and “2”, the result is

$$T_{\text{strong}}^{-1} = 4\sqrt{\pi} n r_p^2 \sigma \left(1 + \frac{GM}{2r_p \sigma^2} \right), \quad (16)$$

where σ is the one-dimensional velocity dispersion, and we have substituted eq. (9) for S_{strong} . For collisions, we plug in S_{coll} to find

$$T_{\text{coll}}^{-1} = 16\sqrt{\pi} n_{\text{single}} \langle R_*^2 \rangle \sigma \left(1 + \frac{G \langle MR_* \rangle}{2\sigma^2 \langle R_*^2 \rangle} \right), \quad (17)$$

where we explicitly show which quantities we average, and n_{single} is the number density of single stars. Similarly for binary–binary interactions:

$$T_{\text{bb}}^{-1} = 16\sqrt{\pi} n_{\text{bin}} X_{\text{bb}}^2 \langle a^2 \rangle \sigma \left(1 + \frac{G \langle Ma \rangle}{2\sigma^2 X_{\text{bb}} \langle a^2 \rangle} \right), \quad (18)$$

and binary–single interactions:

$$T_{\text{bs}}^{-1} = 4\sqrt{\pi} n_{\text{single}} X_{\text{bs}}^2 \langle a^2 \rangle \sigma \left(1 + \frac{G \langle M \rangle \langle a \rangle}{\sigma^2 X_{\text{bs}} \langle a^2 \rangle} \right), \quad (19)$$

where n_{bin} is the number density of binaries, and a is the binary semimajor axis.

2.7. Initial Conditions

For our initial cluster models we use both isolated Plummer models and tidally-truncated King models of varying concentration. Our prescription for tidal mass loss is described in detail in Joshi et al. (2001). For models with a mass spectrum or binaries we assume no primordial mass segregation of the heavier components. We use a binary fraction f_b from 0 to 1, with the binary fraction defined as $f_b = N_b / (N_s + N_b)$, where N_s is the number of single stars in the cluster, N_b is the number of binaries, and $N = N_s + N_b$.

In assigning the initial properties of the binary population, we start with a cluster of only single stars. We create each binary by randomly choosing a cluster star to be the primary member of the binary, and assigning the secondary mass using a flat distribution for the binary mass ratio q ($dP/dq \propto 1$), truncated at the low end so that the mass of the secondary is not lower than the minimum of the initial mass function. With the masses of both binary members set, the remaining binary properties are set according to one of two different schemes. The first is the scheme that has traditionally been used in numerical modeling of dense stellar systems, in which the binary binding energy E_b is distributed uniformly in the logarithm ($dP/dE_b \propto E_b^{-1}$), with fixed upper and lower limits. As shown in Table 1, we take as limits on the binding energy a few kT on the low end to several hundred kT on the high end, where kT is the thermal energy in the cluster core, evaluated as $\frac{1}{3} \langle mv^2 \rangle \approx \langle m \rangle \sigma_c^2$, where σ_c is the one-dimensional velocity dispersion in the core. With the semimajor axis set by the binding energy, the eccentricity e is set according to the thermal distribution ($dP/de = 2e$). The second scheme is a slightly modified version of the first in which the limits on the binding energy and eccentricity are set in a more physical way. The binding energy is still distributed as $dP/dE_b \propto E_b^{-1}$, but with the upper limit set to the binding energy at a semimajor axis of $5(R_1 + R_2)$, where R_i are the stellar radii. The lower limit on the binding energy is set to that of a binary whose lightest member has orbital speed $X_{\text{hs}} \langle v_{\text{rel}} \rangle$, where X_{hs} is as defined in section 2.4.2, and $\langle v_{\text{rel}} \rangle$ is the locally averaged relative velocity between objects, taken to be $4\sigma/3\pi$, where σ is the local three-dimensional velocity dispersion. The eccentricity is set according to the thermal distribution with an upper limit at the eccentricity at which the stars touch at pericenter. Note that when physical limits on E_b are used, the resulting cluster simulation is no longer scalable in its length, mass, and time units, since adopting stellar radii sets the physical scale of the system.

3. EXAMPLE RESULTS AND COMPARISONS

Having verified that our code properly treats two-body relaxation and correctly samples the interaction rates for strong interactions, we now use it to study the evolution of more realistic clusters. We first consider clusters of equal-mass stars with primordial binary populations. Note again that for all simulations presented in this paper physical stellar collisions were turned off. The focus of this section is on presenting a few illustrative results in detail, and comparing the results of our newly modified code with those of other codes, as well as the previous version of our code.

Fig. 9 shows the evolution of an isolated Plummer

model with $N = 10^5$ stars, and an initial 3% binary fraction (model pl_n1e5_fb0.03 in Table 1). The top panel shows M_b , the total mass in binaries bound to the cluster (solid line), and M , the total mass of the cluster (dashed line) as a function of time, relative to their initial values. The middle panel shows E_{bb} , the cumulative energy generated in binary–binary interactions (solid line) and E_{bs} , the cumulative energy generated in binary–single interactions (dashed line) relative to $|E_{c,0}|$, the absolute value of the cluster’s initial mechanical energy. The bottom panel shows the evolution of r_c , the cluster core radius (solid line), $r_{h,b}$, the half-mass radius of the binaries (dashed line), and $r_{h,s}$, the half-mass radius of single stars (dot-dashed line). The evolution of this model is typical of a cluster with primordial binaries. The core initially shrinks until the central density increases to the point at which energy generation in binary interactions is sufficient to prevent the core from collapsing. The binaries steadily gain binding energy in the subsequent, long-lived binary burning phase. They thus suffer progressively larger kinetic recoil from binary interactions, with the result that eventually the half-mass radius of binaries overtakes the single star half-mass radius. Eventually the binary population is sufficiently depleted in the core that the core collapses. The core rebounds quickly once a temperature inversion is triggered there (by binary interactions), resulting in a series of gravothermal core oscillations (the gravothermal nature of which we demonstrate below). A large fraction of the initial binary population is depleted before the core collapses ($\sim 90\%$). The binaries are lost either by being disrupted or ejected in binary interactions. From the middle panel it is clear that a significant fraction of energy can be released via binary interactions, in this case of order the initial cluster mechanical energy.

Fig. 10 shows the evolution of the virial ratio and the total cluster energy (cluster mechanical energy plus binary binding energy) for the same model. The virial ratio is conserved to within statistical fluctuations for the duration of the calculation, suggesting that the code is yielding accurate results. The total cluster energy is also conserved relatively well throughout the calculation, at the level of $\sim 1\%$, with the largest jumps in the energy occurring during the deep core collapse phases. Note that these jumps in the energy are due to soft binaries being broken manually (i.e., not via binary interactions), whose binary binding energy was not added back into the cluster as kinetic energy. Thus the increase in the total cluster energy is due to the decrease in binary binding energy. The cluster mechanical energy is conserved at the level of $< 0.1\%$ during the deep core collapse phases. The high degree of conservation of energy and of the virial ratio for this model is typical of all models we present in this paper.

3.1. Gravothermal Oscillations

It is useful to verify that the core oscillations observed in Fig. 9 are indeed gravothermal in nature, and not a code artifact. Gravothermal oscillations are driven by the gravothermal instability (essentially the negative heat capacity of gravitational systems, which causes heat to flow from cold to hot in a runaway fashion). At any given time during deep core collapse, the temperature profile is a monotonically decreasing function of r , with the central

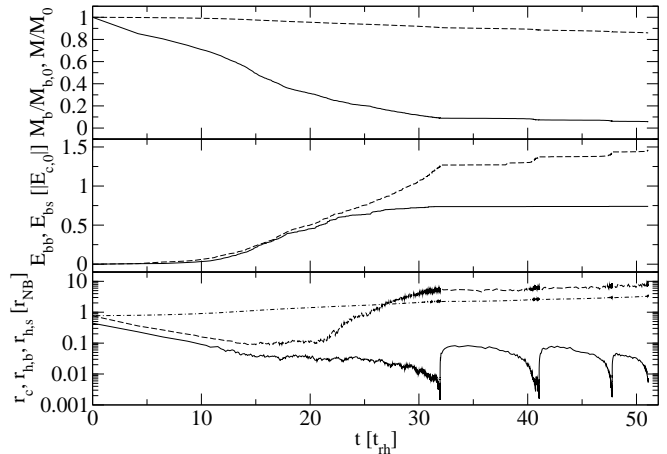


FIG. 9.— Evolution of an isolated Plummer model with $N = 10^5$ stars, and an initial 3% binary fraction (model pl_n1e5_fb0.03 in Table 1). The top panel shows M_b , the total mass in binaries bound to the cluster (solid line), and M , the total mass of the cluster (dashed line) as a function of time, relative to their initial values. The middle panel shows E_{bb} , the cumulative energy generated in binary–binary interactions (solid line) and E_{bs} , the cumulative energy generated in binary–single interactions (dashed line) relative to $|E_{c,0}|$, the absolute value of the cluster’s initial mechanical energy. The bottom panel shows the evolution of r_c , the cluster core radius (solid line), $r_{h,b}$, the half-mass radius of the binaries (dashed line), and $r_{h,s}$, the half-mass radius of single stars (dot-dashed line). Time is in initial half-mass relaxation times.

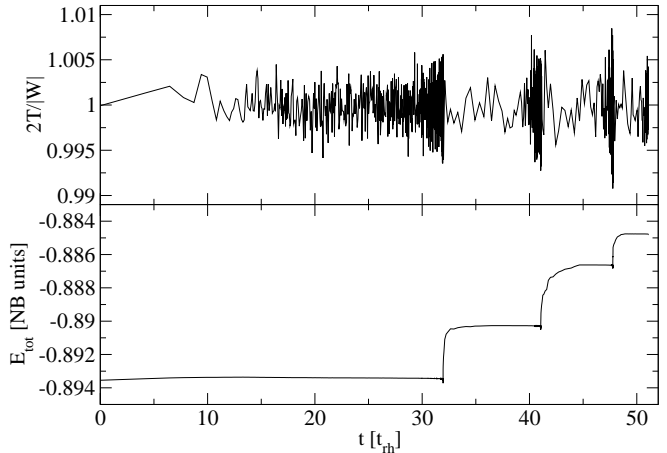


FIG. 10.— Evolution of the virial ratio (top panel), and total cluster energy (bottom panel) for model pl_n1e5_fb0.03. The energy plotted here includes not only the mechanical energy of the cluster, but also the binding energy of the binaries. Note the range on the y axis for the energy plot. In this run energy was conserved to a part in $\sim 10^2$.

temperature steadily increasing as a function of time. At some point during the collapse, a binary scattering interaction occurs, producing a small amount of energy in the core and cooling it, creating a temperature inversion. Once the temperature inversion is established, the gravothermal instability takes over and drives the subsequent core expansion. There are several hallmarks of gravothermal oscillations. One is, of course, a temperature inversion in the cluster core at the point when the core begins to rebound. Another is that the expansion

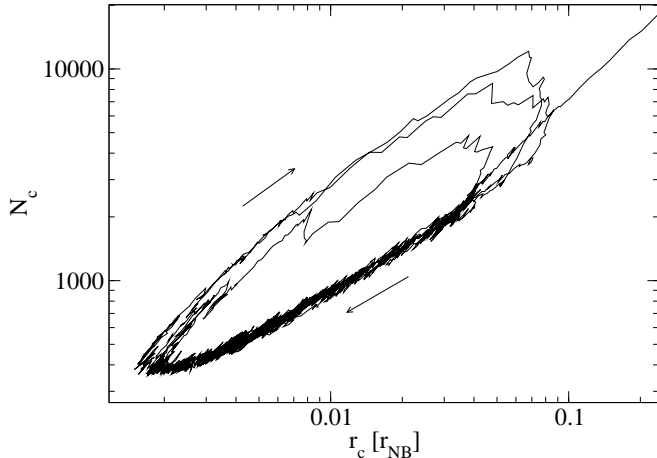


FIG. 11.— Demonstration of the gravothermal nature of the core oscillations in the simulation of model `pl_n1e5_fb0.03`. Plotted here is the number of stars in the core as a function of the core radius. Clockwise loops in this plot suggest that the core oscillations are gravothermal in nature.

phase is not driven by energy generation in binaries. Yet another is the presence of loops in a phase space diagram of the cluster core properties (Makino 1996; Heggie et al. 2006). In Fregeau et al. (2003) we demonstrated the gravothermal nature of the core oscillations produced by our code by displaying the temperature inversion in the core. In the current paper we instead consider the evolution of the core radius and number of stars in the core and look for loops. Fig. 11 plots these two quantities, showing three successive clockwise loops, and suggesting that the core oscillations are gravothermal in nature. Confirmation comes from Fig. 9, showing that there is no significant energy generation due to binary interactions during the core expansion phases.

3.2. Comparison with Theory

For the first quantitative test of our results for the quasi steady-state binary burning phase, we appeal to the semi-analytical model of Vesperini & Chernoff (1994). Their model combines the results of binary scattering experiments with an analytical prescription for energy balance in the core, yielding a relationship among the core binary fraction, the properties of the binary population, and the ratio r_c/r_h :

$$\frac{r_c}{r_h} = \frac{0.1872}{\log_{10}(\gamma N)} \frac{\mu_{bs}\phi_b(1-\phi_b) + \mu_{bb}\phi_b^2}{(1+\phi_b)^4} \left(\frac{v_c}{v_h}\right)^3 \left(\frac{\Gamma}{10}\right), \quad (20)$$

where ϕ_b is the core binary fraction, μ_{bs} and μ_{bb} are coefficients representing the energy generation rates in binary–single and binary–binary interactions for a given set of binary properties, v_c and v_h are the core and half-mass velocity dispersions, and Γ parameterizes the expansion rate of the core in terms of the half-mass relaxation time. Heggie et al. (2006) have shown that eq. (20) agrees well with the results of N -body simulations of $N = 4096$ clusters with primordial binaries, with the values $\Gamma = 9.4$ and $v_c/v_h = \sqrt{2}$, which are close to the canonical values of $\Gamma = 11.5$ and $v_c/v_h = \sqrt{2}$ adopted in Vesperini & Chernoff (1994). However, they find that

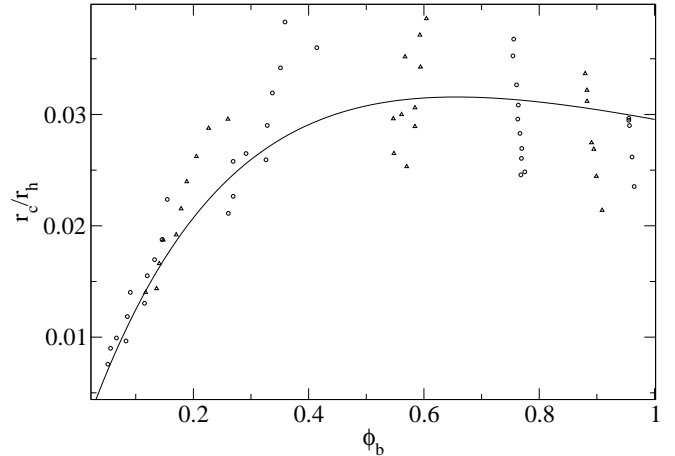


FIG. 12.— The quantity r_c/r_h vs. core binary fraction ϕ_b for simulations `pl_n3e5_fb0.01_kt` through `pl_n3e5_fb0.60_kt`, compared with the semi-analytical model of Vesperini & Chernoff (1994). Each set of points (shown as circles and triangles, alternating) represents a simulation with a different initial binary fraction (from left to right): $f_b = 0.01, 0.02, 0.04, 0.08, 0.15, 0.3,$ and 0.6 . Each point is determined by averaging over every 10^3 timesteps after core stabilization to several t_{rh} beyond. Note that the theoretical model is scaled down by a factor of 2.5 from the standard values $\Gamma = 10$ and $v_c/v_h = \sqrt{2}$, in good agreement with an extrapolation of the results of Heggie et al. (2006).

the dependence of r_c/r_h on N is steeper than eq. (20), in the sense that clusters with $N \gtrsim 10^3$ have a systematically smaller value of r_c/r_h than eq. (20) predicts, with the opposite true for clusters with fewer stars. Extrapolating from the numerical results in Fig. 18 of Heggie et al. (2006), it appears that for $N \sim 10^5$ eq. (20) overestimates r_c/r_h by a factor of ≈ 2 for the values $\Gamma = 10$ and $v_c/v_h = \sqrt{2}$.

To test the agreement between our code and eq. (20), we have performed several cluster simulations of varying initial binary fraction and measured the core radius and binary fraction after core stabilization. The details of the models (`pl_n3e5_fb0.01_kt` through `pl_n3e5_fb0.60_kt`) are given in Table 1. Fig. 12 shows r_c/r_h vs. core binary fraction ϕ_b for the simulations, compared with eq. (20). Each set of points (shown as circles and triangles, alternating) represents a simulation with a different initial binary fraction. Each point is determined by averaging over every $\sim 10^3$ timesteps after core stabilization to several t_{rh} beyond. The agreement between our code and the semi-analytical model appears to be quite satisfactory, with the data points following the functional form of the model on ϕ_b . For the proper normalization of r_c/r_h , however, we had to scale eq. (20) down by a factor of 2.5 from the standard values $\Gamma = 10$ and $v_c/v_h = \sqrt{2}$. (For the remaining parameters, we used the standard value $\gamma = 0.11$, while μ_{bs} and μ_{bb} are fixed by the initial conditions.) Quantitatively, the discrepancy between eq. (20) and our numerical results is nearly identical to an extrapolation of the N -body simulations of Heggie et al. (2006), implying that our Monte Carlo results for the evolution of cluster structural parameters may agree well with N -body simulations of clusters with $N \sim 10^5$.

3.3. Comparison with Previous Numerical Work

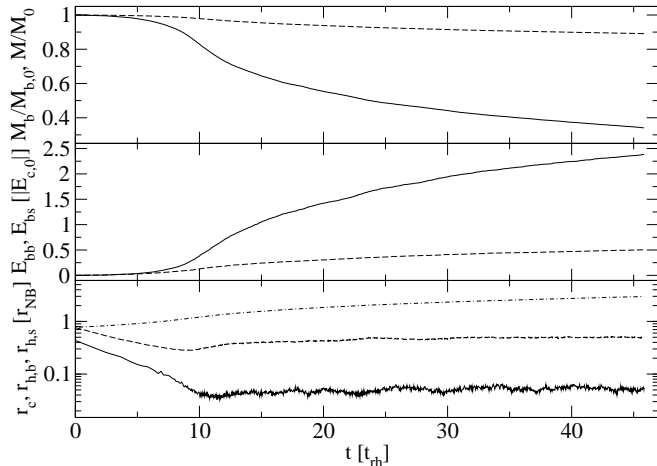


FIG. 13.— Evolution of the “Gao, et al.” model: an isolated Plummer model with $N = 3 \times 10^5$ objects, equal-mass stars, and 10% binaries (model T4). Quantities plotted are the same as in Fig. 9.

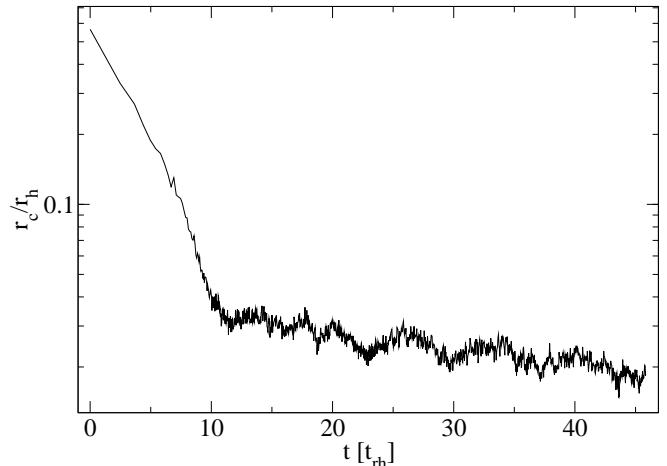


FIG. 14.— Evolution of r_c/r_h for model T4.

The amount of numerical work reported on clusters with primordial binaries has grown considerably since the work of Gao et al. (1991), who used a multimass Fokker-Planck code coupled with a recipes-based treatment of binary interactions. In a previous paper (Fregeau et al. 2003), we used a Monte Carlo code coupled with recipes for binary interactions. Giersz & Spurzem (2003) used a hybrid code, which treated single stars via a gas dynamical method and binaries via Monte Carlo, and performed direct numerical integration of binary interactions. Heggie et al. (2006) and Trenti et al. (2006) performed direct N -body simulations. And as described in the preceding sections, in this paper we use a Monte Carlo method coupled with direct numerical integration of binary interactions. In this section we compare the results from our code with those from all the methods just listed.

A standard model has emerged in the business of simulating the evolution of clusters containing primordial binaries. The “Gao, et al.” model is an isolated Plummer model with $N = 3 \times 10^5$ objects, equal-mass stars, and 10% binaries, with the binary binding energy distributed uniformly in the logarithm from 3 to $400kT$, and with the binary eccentricity distributed according to the thermal distribution. Since this model has been treated by all the previous work cited above, we use it as a basis for comparison. Fig. 13 shows the evolution of this model (T4 in Table 1). Fig. 14 shows the evolution of the ratio r_c/r_h . Although we did not integrate our model long enough for gravothermal oscillations to take place (they start at $t \approx 50t_{\text{th}}$ in the model of Gao et al. (1991), and our model stops at about $45t_{\text{th}}$), there are still ample results for comparison. Comparing with Fig. 1 of Gao et al. (1991), the timescale of the initial core contraction we find is nearly identical at $\approx 10t_{\text{th}}$. This is the same timescale found by Heggie et al. (2006) in their Fig. 2 and Giersz & Spurzem (2003) in their Fig. 4, although in the latter case the comparison is less meaningful since their results show no long-lived binary burning phase. It is also similar to the result of Fregeau et al. (2003) in their Fig. 4, although they find a slightly shorter timescale.

Turning now to the size of the core radius during the bi-

nary burning phase, we find $r_c \approx 0.040$ in N -body units. The model of Gao et al. (1991) shows an almost identical core size, with $r_c \approx 0.046$ in N -body units (note that the unit of length in their plot is $3\pi/16$ in N -body units). This is somewhat expected, since the code of Gao et al. (1991) predicts a smaller core than the semi-analytical theory (Heggie et al. 2006). The model of Fregeau et al. (2003) shows a much larger core, with $r_c \approx 0.2$. This is not surprising, since recipes tend to overestimate the energy generation rate in binary interactions (Fregeau et al. 2003; Giersz & Spurzem 2003; Fregeau et al. 2005). Although the model of Giersz & Spurzem (2003) does not show a long-lived binary burning phase, there is a subtle hint of a short-lived one with $r_c \approx 0.2$. This is also much larger than the value we find. Comparing our Fig. 14 with Fig. 2 of Heggie et al. (2006), we see qualitatively very similar behavior in the two calculations, with r_c/r_h abruptly slowing its contraction at $t \approx 10t_{\text{th}}$ and steadily decreasing thereafter. At the start of the binary-burning phase, Heggie et al. (2006) find $r_c/r_h \approx 0.06$, while we find $r_c/r_h \approx 0.03$. Corrected for particle number via eq. (20), their value becomes $r_c/r_h \approx 0.05$. Taking into account the systematic overestimate of r_c/r_h for $N \gtrsim 10^3$ by eq. (20) described in section 3.2, their value becomes $r_c/r_h \approx 0.03$, rendering the agreement quite satisfactory. We can also compare with Gao et al. (1991), who find a value $r_c/r_h \approx 0.03$, in good agreement with our results. The agreement in this last comparison is rather surprising, since Gao et al. (1991) used recipes for binary interactions, which are known to artificially inflate the core radius. In terms of the structural parameters during the binary burning phase (which, as the longest-lived evolutionary phase in the life of a cluster is the most observationally relevant), as well as the timescale to reach it, our code appears to agree well with N -body, slightly less well with the Fokker-Planck code, and much less well with the two other approximate codes.

We can also compare the mass in binaries (or, equivalently, number) as a function of time. At the somewhat arbitrary time of $40t_{\text{th}}$, we find $M_b/M_{b,0} \approx 0.37$. Gao et al. (1991) find a value of 0.41, while Heggie et al. (2006) find a value of 0.36. Fregeau et al. (2003) find a

value of 0.35. All these methods appear to agree very well on the average rate that binaries are lost (either ejected or disrupted in binary interactions) up to $40t_{\text{rh}}$, although the agreement with Fregeau et al. (2003) is probably fortuitous given the disagreement in the structural parameters.

Comparing an isolated cluster model tests in combination how well our code treats two-body relaxation, mass segregation, and the various aspects of binary burning. Having shown that our code agrees well with the “exact” method of N -body, one can be fairly confident that our code treats these processes relatively accurately. However, since all dense star clusters are tidally truncated to some degree, it is still useful to consider how well our code treats the physics of tidal stripping. As described in Joshi et al. (2001), we use a cutoff radius criterion to determine whether a star has been stripped from the cluster. This is in contrast to the more accurate technique of including the tidal field in the equations of motion (which is not possible for the Monte Carlo method). Trenti et al. (2006) have compared the two tidal stripping methods by performing N -body simulations of $N \sim 10^4$ clusters with primordial binaries, and have found that models using a tidal cutoff tend to survive longer before disrupting (up to a factor of ~ 2 , although it’s not clear how this factor scales with N), and have a larger core radius (again, up to a factor of ~ 2), than models with a tidal field. We will keep this in mind when presenting results below. For now we compare two current simulations with the tidal cutoff models of Trenti et al. (2006), and with the previous version of our code. Figs. 15 and 16 show the evolution of models w3_n3e5_fb0.1 and w7_n3e5_fb0.1, respectively. Comparing the first with Fig. 13 of Fregeau et al. (2003), we see that although both models reach disruption, our new results are qualitatively different in behavior, yielding what appears to be a binary burning phase from $10t_{\text{rh}}$ to disruption, while the old result shows no such phase. Aside from this difference, the quantitative evolution of the structural radii, the total cluster and binary mass, and the disruption timescale appear to be very similar between the two models. Comparing with Fig. 16 of Trenti et al. (2006), we find similar qualitative behavior, with a hint of a binary burning phase in their results starting at roughly the same time, similar evolution of the structural radii, and both models resulting in disruption at $\sim 15t_{\text{rh}}$. Our model seems to predict a higher rate of binary destruction, however. Our model also predicts a smaller core radius, by a factor of ~ 3 . This is likely explained by the N dependence of r_c/r_h , as described in section 3.2.

Moving on to the $W_0 = 7$ model, we find similar qualitative behavior and disruption times as both Fregeau et al. (2003) in their Fig. 10 and Trenti et al. (2006) in their Fig. 17. However, the model of Fregeau et al. (2003) predicts a much larger core radius in the binary burning phase than our current model. This is due to the fact that the recipes used in that calculation tend to overestimate the rate of energy generation in binary burning. The agreement with Trenti et al. (2006) is much better, with our core radius being, again, a factor of ~ 3 smaller than the N -body result. Looking at M and M_b , our model again appears to predict a higher rate of binary destruction than the N -body model. Finally, we note that both with our current code and with the previous version, this

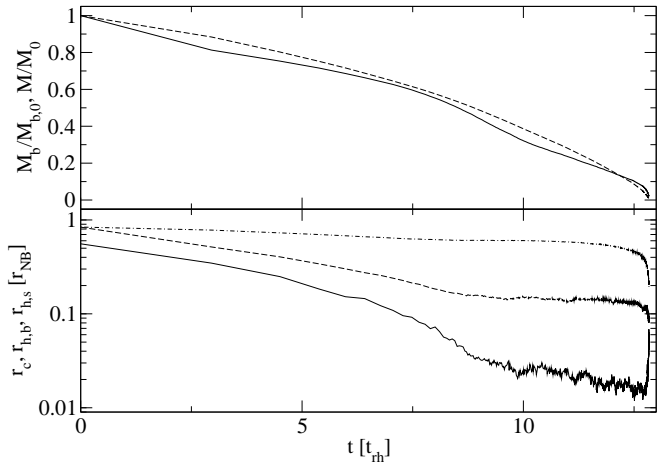


FIG. 15.— Evolution of model w3_n3e5_fb0.1. Quantities plotted are the same as in Fig. 9.

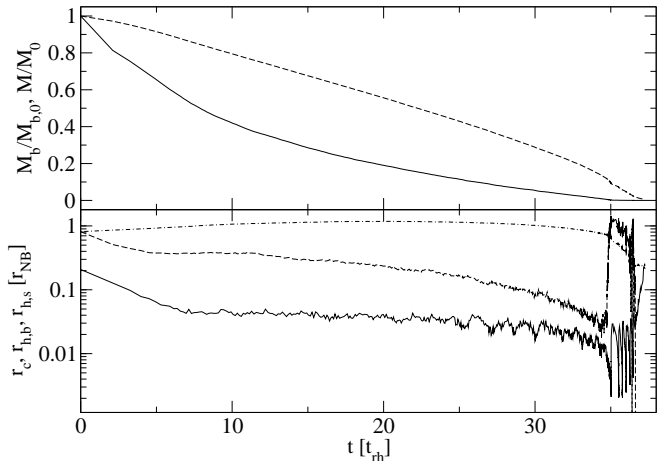


FIG. 16.— Evolution of model w7_n3e5_fb0.1. Quantities plotted are the same as in Fig. 9.

model undergoes deep core collapse and gravothermal oscillations just before disruption, while the N -body calculation does not. As mentioned in Heggie et al. (2006), this discrepancy may not be significant, since the dependence of the deep core collapse timescale on N is not fully understood.

In general, the results of our new code yield much improved agreement with the N -body results reported in the literature, for both isolated and tidally-truncated models. The remaining discrepancies are in areas where the dependence of the results on N is not fully understood, meaning that more detailed comparisons must await improved theory or N -body calculations with larger N (Monte Carlo simulations become less valid as N is decreased).

4. RESULTS AND COMPARISON WITH OBSERVATIONS

In addition to displaying the initial conditions for all models simulated for this paper, Table 1 gives several important measured quantities for each simulation. The first is the core stabilization time, t_{cs} , at which the core radius stabilizes (i.e., the start of the binary-burning

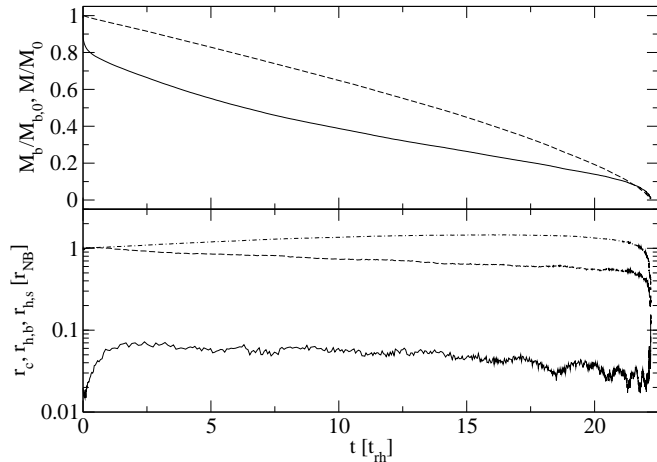


FIG. 17.— Evolution of model w11_n3e5_fb0.3. Quantities plotted are the same as in Fig. 9.

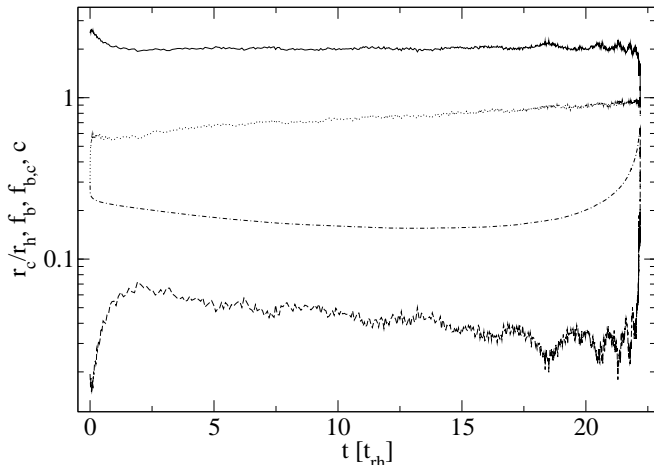


FIG. 18.— Evolution of r_c/r_h (dashed line), total cluster binary fraction f_b (dot-dashed line), core binary fraction $f_{b,c}$ (dotted line), and concentration c (solid line) for model w11_n3e5_fb0.3.

phase) after the initial contraction or expansion. Note that some authors denote this as the core collapse time when discussing clusters with primordial binaries. The second is the time of the first deep core collapse, t_{cc} , which, for models with binaries, represents the time at which the binary population is nearly depleted in the core. The next is the disruption time, t_{dis} , for models which are tidally truncated. The next is r_c/r_h , the ratio of the core to half-mass radius averaged over a few t_{rh} after t_{cs} . Finally, $c = \log_{10}(r_t/r_c)$ is the concentration parameter averaged over the same time period. The evolution of several of the models in the table has been shown graphically in the preceding figures. The behavior of the remaining models is similar to the ones already shown, with the relevant timescales and structural parameters appropriately modified. The only exceptions are the high concentration King models, which undergo an initial phase of core expansion (instead of contraction) due to their initially very dense state. Fig. 17 displays the evolution of such a model, model w11_n3e5_fb0.3. For reference we have plotted the time evolution of the mea-

sured quantities r_c/r_h and c in Fig. 18, along with the the total cluster binary fraction f_b and the core binary fraction $f_{b,c}$. The sudden drop in the binary fraction at the start of the simulation is due to the destruction of binaries near the edge of the hard-soft boundary. It is largely an artifact caused by our routine for using physical limits to set the initial properties of the binary population, since it uses the local velocity dispersion to determine whether or not a binary is hard, and not the central velocity dispersion. Note that when using kT -based limits, we measure kT in the cluster core.

There are several trends apparent in the data presented in Table 1. For fixed initial cluster structure, as f_b is increased from zero, t_{cs} decreases from the value of t_{cc} at $f_b = 0$, reaches a minimum around $f_b \sim 0.2$, then increases back to approximately its $f_b = 0$ value for $f_b = 1$. This dip is due to the fact that in the initial core contraction or expansion phase, binaries act primarily as a second, heavier star species, hastening cluster energy transport via mass segregation. Looking at the deep core collapse times, another clear trend is that t_{cc} increases dramatically as f_b is increased. This trend is most striking in the isolated Plummer models, with merely $f_b \approx 0.03$ being enough to double the deep core collapse time, and $f_b = 1$ increasing it by a factor of at least 25. The physical explanation is, of course, that the lifetime of the binary-burning phase increases with the amount of fuel available, in analogy to hydrogen-burning in main-sequence stars. Looking more carefully at the tidally-truncated King models, we see that the presence of binaries tends to drive these clusters to complete tidal disruption. The minimum of t_{dis} occurs somewhere in the range $0.1 \lesssim f_b \lesssim 1$. This is not surprising, since the maximum of r_c/r_h occurs at $f_b \approx 0.7$ (see Fig. 12), implying that the cluster is the most distended for this value of f_b . Moving now to the cluster structural parameters, we see that there is relatively little variation in r_c/r_h and c over the wide range of cluster initial profiles and binary fractions considered, with r_c/r_h ranging from ~ 0.02 for Plummer or $W_0 \sim 7$ King models with low f_b , to ~ 0.08 for larger or smaller W_0 King models with $f_b \sim 1$. The concentration parameter shows a similarly small amount of variation, peaking at ~ 2.5 for $W_0 \sim 7$ and low binary fraction, and falling to ~ 2.0 for smaller or larger W_0 and larger binary fraction. As expected, a larger f_b leads to a smaller c , since the core radius generally increases with binary fraction. Another trend is evident when comparing single-mass models with models incorporating a more realistic mass spectrum (Salpeter from 0.2 – $1.2 M_\odot$): models with a mass spectrum tend to have a slightly smaller r_c/r_h , and show more variation of c with W_0 .

Although our cluster evolution models are rather simplified (since they do not include single- or binary-star stellar evolution, or collisions), it is still useful to compare the predicted structural parameters with observations. In Fregeau et al. (2003) we compared r_c/r_h and c from simulations using the previous version of our Monte Carlo code (which includes recipes for binary interactions instead of dynamical integrations), with observations for the Galactic globular clusters. There we found promising agreement, with r_c/r_h from the simulations falling generally in the low r_c/r_h tail of the observed distribution for non-core collapsed clusters, which extends from ~ 0.1 to

~ 1 with a peak at ~ 0.5 . And similarly for c , falling in the high c tail of the observed distribution for non-core collapsed clusters, which extends from ~ 0.5 to ~ 2.5 with a peak at ~ 1.5 . However, as described above, we find systematically smaller values for r_c/r_h than Fregeau et al. (2003) by a factor of ~ 10 , as well as systematically larger values for c by ~ 0.5 . The improved treatment of binary interactions in our code has shifted our predictions for r_c/r_h and c outside the observed ranges for non-core collapsed clusters, now yielding agreement only with the roughly 10% of Galactic globular clusters that are classified observationally as core collapsed.

A globular cluster of comparable mass stars with $f_b \gtrsim 0.03$ viewed at a random time during its life has a greater than 50% chance of being found in the quasi-steady state binary burning phase. When one considers that globulars are likely born with significant binary fractions (Hut et al. 1992; Ivanova et al. 2005), and that we are currently observing the Galactic globular clusters at a late stage in their evolution, the vast majority of observed clusters should currently be in the binary-burning phase. The most obvious interpretation is that most Galactic globular clusters are currently in the binary-burning phase, and the roughly 10% that are observationally classified as core-collapsed are within a small time window around a deep core collapse phase. The disagreement between simulations and observations for the structural parameters of the non core-collapsed clusters, then, suggests one of at least two possibilities: 1) the Galactic globular clusters do not start within the volume in parameter space of initial conditions we have considered here; or 2) there are additional physical processes at work in clusters, yielding larger cores. If clusters are born with $W_0 \lesssim 3$ or $W_0 \gtrsim 11$ and $f_b \lesssim 1$, extrapolation of our results suggests that simulations may then agree with the observations of non-core collapsed clusters, implying possibility (1) may be correct. This does not take into account the observed core binary fractions of globular clusters, which are typically much lower than what one would find in a simulation starting with $f_b \gtrsim 0.4$. Note also that observations of the less relaxed clusters suggest that they are more likely to have been born with $W_0 \lesssim 3$ rather than $W_0 \gtrsim 11$. In addition, we have not included in our simulations any form of stellar evolution (for single stars or binaries), or physical stellar collisions. Single star evolution tends to heat a cluster early in its lifetime via wind-driven mass loss and supernovae explosions, causing the cluster and its core to expand. However, this effect is most pronounced only early in the lifetime of a star cluster ($\lesssim 1$ Gyr). The effects of binary stellar evolution are less obvious, since it is a rather complicated process. However, the simulations of Ivanova et al. (2005) suggest that the binary fraction in the core quickly drops to relatively small values ($\lesssim 20\%$), and that binary stellar evolution tends to destroy tight binaries. The net result is likely to be a smaller equilibrium value of r_c/r_h (Vesperini & Chernoff 1994) than with no binary stellar evolution, suggesting that possibility (2) is less likely. A refined quantitative study combining the results of Ivanova et al. (2005) and Vesperini & Chernoff (1994) would more clearly elucidate this effect.

The effect of direct single–single star collisions in young dense clusters is to dissipate orbital energy and drive core

collapse (Freitag et al. 2006a). For clusters in which stellar merger products have had time to evolve and lose mass through accelerated stellar evolution, the net result may be to heat the core (Lee 1987). The degree to which this process operates in Galactic globular clusters is unclear, however. The effect of stellar collisions during binary interactions is generally to reduce the efficiency of binary burning (Hut & Inagaki 1985; McMillan 1986; Goodman & Hernquist 1991). This is because a merger product resulting from a star–star collision typically has significantly more internal energy (potential and rotational) than the sum of the merging stars’ internal energies. Thus when a collision occurs during a binary dynamical interaction, effectively some of the binding energy of the binary is converted into stellar binding energy, decreasing the efficiency of binary burning. In other words, energy that had previously been available to be converted into kinetic energy through binary interactions is no longer available, tied up in the stars. The result should be a decreased value of r_c/r_h in the binary-burning phase relative to the case of point-mass binary dynamics, implying that possibility (2) is less likely. As with binary stellar evolution, however, a more detailed simulation which studies the effects of collisions in an evolving model should be performed to quantify the effect.

5. SUMMARY AND CONCLUSIONS

In this paper we have described our new Monte Carlo evolution code, and used it to perform a large set of cluster evolution simulations, which we compared with previous results in the literature, as well as observations of Galactic globular clusters.

In section 2 we described our new code in detail, including the implementation of direct integration of binary scattering interactions and star–star physical collisions, and the fundamental modifications we have made to the core Monte Carlo method. We performed several test calculations with the code, finding that it reproduces well several standard results. It yields a core collapse time of $\approx 18 t_{\text{rh}}$ for an isolated Plummer model, in good agreement with results in the literature. It also produces an $r^{-2.3}$ density profile during the late stages of core collapse, in good agreement with the theoretical expectation. We also performed comparisons of clusters with increasingly wide mass spectra with N -body, finding that for moderately wide mass spectra (1 to $10 M_\odot$) the agreement with N -body is satisfactory, but for very wide mass spectra (0.2 to $120 M_\odot$) the agreement is not as good. In particular, for such wide mass spectra, our Monte Carlo code tends to overestimate the mass segregation timescale at early times, and underestimate it at later times. The sense of the disagreement is the same as found by Freitag et al. (2006b) with their Monte Carlo code.

In section 3 we displayed a few example results and compared with theory and previous numerical calculations in the literature. We found that the code conserves energy well over the long timescales of our runs, and verified that the core oscillations it produces are indeed gravothermal in nature. We compared our predicted values of r_c/r_h during the quasi-steady state binary burning phase with the semi-analytical work of Vesperini & Chernoff (1994), finding excellent agreement after cor-

recting the N -dependence of the theory, as described in Heggie et al. (2006). We compared our results with previous numerical results in the literature for isolated and tidally-truncated cluster models, finding excellent agreement with N -body calculations. There are much larger discrepancies with the other approximate methods (Fokker-Planck and other Monte Carlo codes), which is to be expected, since most used recipes for binary interactions, which are known to overestimate the energy generation rate in binaries.

In section 4 we surveyed the results from all our simulations, and compared with observations. Our models cover a large range in parameter space, using Plummer and King models with $W_0 = 3$ to 11 for the initial cluster profile, and with initial binary fractions from 0 to 1. The resulting structural parameters in the binary burning phase span a remarkably small range, with r_c/r_h varying from 0.02 to 0.08, and c varying from 1.9 to 2.6. Our results for these structural parameters are distinctly different from the results found with the previous version of our code (which used recipes for binary interactions), with r_c/r_h now smaller than Fregeau et al. (2003) by a factor of ~ 10 , and with c larger by ~ 0.5 . Although our new results agree much better with N -body calculations, they unfortunately agree much less well than in Fregeau et al. (2003) with the observations. The disagreement implies one of at least two possibilities. It may be that the initial conditions for Galactic globular clusters are

outside the range of initial conditions we have sampled in this work. Extrapolation of our results suggests that clusters with $W_0 \lesssim 3$ or $W_0 \gtrsim 11$ and $f_b \lesssim 1$ may match the observations. This does not take into account the observed core binary fractions of globular clusters, which are typically much lower than what one would find in a simulation starting with $f_b \gtrsim 0.4$. Note also that observations of the less relaxed clusters suggest that they are more likely to have been born with $W_0 \lesssim 3$ rather than $W_0 \gtrsim 11$. Alternatively, stellar evolution and collisions, which are not included in the simulations in this paper, could possibly explain the disagreement. However, it appears that the effect of these processes should act in the opposite sense of ameliorating the disagreement with observations. More detailed simulations including the effects of single- and binary-star evolution and physical collisions should be performed to test this.

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TABLE 1
 PARAMETERS AND MEASURED QUANTITIES FOR ALL MODEL SIMULATIONS PRESENTED IN THIS PAPER.

name	N	profile	r_{NB}/pc	$f(M/M_{\odot})$	f_b	$f(E_b/kT)$	$t_{\text{cs}}/t_{\text{rh}}$	$t_{\text{cc}}/t_{\text{rh}}$	$t_{\text{dis}}/t_{\text{rh}}$	r_c/r_h	c
T1	5×10^5	Plum.	1.02	$\propto \delta(M-1)$	0	17.6
T2	10^6	Plum.	0.58	Kroup., 0.1–10	0	0.54
T3	1.25×10^6	Plum.	0.60	Salp., 0.2–120	0	0.067
T4	3×10^5	Plum.	5.60	$\propto \delta(M-1)$	0.1	$\propto E_b^{-1}$, 3–400	10	> 56	...	0.03	...
pl_n1e5_fb0.03	10^5	Plum.	7.33	$\propto \delta(M-1)$	0.03	$\propto E_b^{-1}$, phys.	15	31.9	...	0.03	...
pl_n3e5_fb0.01_kt	3×10^5	Plum.	5.44	$\propto \delta(M-1)$	0.01	$\propto E_b^{-1}$, 10–100	17	> 23	...	0.02	...
pl_n3e5_fb0.02_kt	3×10^5	Plum.	5.46	$\propto \delta(M-1)$	0.02	$\propto E_b^{-1}$, 10–100	15	> 29	...	0.03	...
pl_n3e5_fb0.04_kt	3×10^5	Plum.	5.49	$\propto \delta(M-1)$	0.04	$\propto E_b^{-1}$, 10–100	12	> 37	...	0.04	...
pl_n3e5_fb0.08_kt	3×10^5	Plum.	5.56	$\propto \delta(M-1)$	0.08	$\propto E_b^{-1}$, 10–100	11	> 39	...	0.04	...
pl_n3e5_fb0.15_kt	3×10^5	Plum.	5.68	$\propto \delta(M-1)$	0.15	$\propto E_b^{-1}$, 10–100	10	> 49	...	0.04	...
pl_n3e5_fb0.30_kt	3×10^5	Plum.	5.92	$\propto \delta(M-1)$	0.3	$\propto E_b^{-1}$, 10–100	13	> 54	...	0.03	...
pl_n3e5_fb0.60_kt	3×10^5	Plum.	6.34	$\propto \delta(M-1)$	0.6	$\propto E_b^{-1}$, 10–100	18	> 54	...	0.03	...
pl_n3e5_fb0	3×10^5	Plum.	5.42	$\propto \delta(M-1)$	0	17.6
pl_n3e5_fb0.03	3×10^5	Plum.	5.48	$\propto \delta(M-1)$	0.03	$\propto E_b^{-1}$, phys.	16	31.5	...	0.03	...
pl_n3e5_fb0.1	3×10^5	Plum.	5.60	$\propto \delta(M-1)$	0.1	$\propto E_b^{-1}$, phys.	11	> 100	...	0.04	...
pl_n3e5_fb0.3	3×10^5	Plum.	5.92	$\propto \delta(M-1)$	0.3	$\propto E_b^{-1}$, phys.	12	> 240	...	0.04	...
pl_n3e5_fb1	3×10^5	Plum.	6.83	$\propto \delta(M-1)$	1	$\propto E_b^{-1}$, phys.	20	> 460	...	0.04	...
w3_n3e5_fb0	3×10^5	$W_0 = 3$	5.42	$\propto \delta(M-1)$	0	13.4
w3_n3e5_fb0.03	3×10^5	$W_0 = 3$	5.48	$\propto \delta(M-1)$	0.03	$\propto E_b^{-1}$, phys.	11	14.1	14.7	0.05	2.0
w3_n3e5_fb0.1	3×10^5	$W_0 = 3$	5.60	$\propto \delta(M-1)$	0.1	$\propto E_b^{-1}$, phys.	9	...	12.8	0.05	1.9
w3_n3e5_fb0.3	3×10^5	$W_0 = 3$	5.92	$\propto \delta(M-1)$	0.3	$\propto E_b^{-1}$, phys.	10	...	12.0	0.05	1.9
w3_n3e5_fb1	3×10^5	$W_0 = 3$	6.83	$\propto \delta(M-1)$	1	$\propto E_b^{-1}$, phys.	13	...	16.4	0.06	1.9
w7_n3e5_fb0	3×10^5	$W_0 = 7$	5.42	$\propto \delta(M-1)$	0	11.1
w7_n3e5_fb0.03	3×10^5	$W_0 = 7$	5.48	$\propto \delta(M-1)$	0.03	$\propto E_b^{-1}$, phys.	11	19.7	> 20	0.03	2.4
w7_n3e5_fb0.1	3×10^5	$W_0 = 7$	5.60	$\propto \delta(M-1)$	0.1	$\propto E_b^{-1}$, phys.	7	35.0	37.3	0.04	2.2
w7_n3e5_fb0.3	3×10^5	$W_0 = 7$	5.92	$\propto \delta(M-1)$	0.3	$\propto E_b^{-1}$, phys.	7	...	33.9	0.05	2.1
w7_n3e5_fb1	3×10^5	$W_0 = 7$	6.83	$\propto \delta(M-1)$	1	$\propto E_b^{-1}$, phys.	13	...	42.1	0.05	2.1
w11_n3e5_fb0	3×10^5	$W_0 = 11$	5.42	$\propto \delta(M-1)$	0	0.60
w11_n3e5_fb0.03	3×10^5	$W_0 = 11$	5.48	$\propto \delta(M-1)$	0.03	$\propto E_b^{-1}$, phys.	1.4	12.7	> 13	0.04	2.2
w11_n3e5_fb0.1	3×10^5	$W_0 = 11$	5.60	$\propto \delta(M-1)$	0.1	$\propto E_b^{-1}$, phys.	2.0	23.5	24.7	0.05	2.1
w11_n3e5_fb0.3	3×10^5	$W_0 = 11$	5.92	$\propto \delta(M-1)$	0.3	$\propto E_b^{-1}$, phys.	2.0	...	22.2	0.06	2.0
w11_n3e5_fb1	3×10^5	$W_0 = 11$	6.83	$\propto \delta(M-1)$	1	$\propto E_b^{-1}$, phys.	3.0	...	27.6	0.08	1.9
pl_n1e5_s_fb0	10^5	Plum.	5.05	Salp., 0.2–1.2	0	4.9
pl_n1e5_s_fb0.03	10^5	Plum.	5.09	Salp., 0.2–1.2	0.03	$\propto E_b^{-1}$, phys.	4.8	> 18	...	0.02	...
pl_n1e5_s_fb0.1	10^5	Plum.	5.17	Salp., 0.2–1.2	0.1	$\propto E_b^{-1}$, phys.	4.7	> 54	...	0.03	...
pl_n1e5_s_fb0.3	10^5	Plum.	5.40	Salp., 0.2–1.2	0.3	$\propto E_b^{-1}$, phys.	5.3	> 140	...	0.04	...
kw4_n1e5_s_fb0	10^5	$W_0 = 4$	5.05	Salp., 0.2–1.2	0	5.36
kw4_n1e5_s_fb0.03	10^5	$W_0 = 4$	5.09	Salp., 0.2–1.2	0.03	$\propto E_b^{-1}$, phys.	5	...	8.3	0.04	2.1
kw4_n1e5_s_fb0.1	10^5	$W_0 = 4$	5.17	Salp., 0.2–1.2	0.1	$\propto E_b^{-1}$, phys.	5	...	8.6	0.04	2.0
kw4_n1e5_s_fb0.3	10^5	$W_0 = 4$	5.40	Salp., 0.2–1.2	0.3	$\propto E_b^{-1}$, phys.	4.6	...	9.0	0.05	1.9
kw8_n1e5_s_fb0	10^5	$W_0 = 8$	5.05	Salp., 0.2–1.2	0	1.00
kw8_n1e5_s_fb0.03	10^5	$W_0 = 8$	5.09	Salp., 0.2–1.2	0.03	$\propto E_b^{-1}$, phys.	0.9	...	> 11	0.02	2.6
kw8_n1e5_s_fb0.1	10^5	$W_0 = 8$	5.17	Salp., 0.2–1.2	0.1	$\propto E_b^{-1}$, phys.	1.0	...	19.3	0.03	2.4
kw8_n1e5_s_fb0.3	10^5	$W_0 = 8$	5.40	Salp., 0.2–1.2	0.3	$\propto E_b^{-1}$, phys.	1.1	...	22.0	0.04	2.3

NOTE. — Here N is the number of total cluster objects (single stars and binaries), the profile is either a Plummer model or a King model with the specified W_0 , r_{NB} is the unit of length in the simulation, $f(M)$ is the initial mass function, f_b is the initial binary fraction, $f(E_b)$ is the distribution of binary binding energy, t_{cs} is the time at which the core radius stabilizes (i.e., the start of the binary-burning phase) after the initial contraction or expansion (note that some authors denote this as the core collapse time when discussing clusters with primordial binaries), t_{cc} is the time of the first deep core collapse, t_{dis} is the time at which the cluster disrupts due to tidal stripping, r_c/r_h is the ratio of the core to half-mass radius averaged over a few t_{rh} after t_{cs} , and $c = \log_{10}(r_t/r_c)$ is the concentration parameter averaged over the same time period. Quantities are omitted when the physical state they describe is never reached (or can never be reached) during the simulation. Note that those models with $f_b = 0$ or those with kT -based limits on E_b have one degree of freedom in their scaling, while those with physical limits on the binary population cannot be rescaled.